



Semi-Symmetric Non Metric Connection on an Almost Contact Metric Manifold

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ABSTRACT

In 1924, Friedmann and Schouten have introduced the idea of Semi-Symmetric linear connection in a differentiable manifold. In 1970, Semi-Symmetric Connection were studied by K. Yano in a Riemannian manifold. In 2008, S. K. Chaubey and R. H. Ojha defined a new Semi-Symmetric non metric and Quarter Symmetric metric connections. The purpose of the present paper is to study some properties of Semi-Symmetric non metric connections in an almost contact metric manifold, several useful Algebraic and geometrical properties have been studied.

KEYWORDS : Semi Symmetric non metric connection, Almost contact metric manifold.

1. Introduction

Let V^n be an n -dimensional C^∞ manifold and let there exists in V^n a vector valued linear function F , a vector Field T and an 1-form A such that

$$F^2 X = -X + A(X)T \tag{1.1}$$

$$\bar{X} \text{ def}^n FX \tag{1.2}$$

For any vector field X . Then V^n is called an almost contact manifold. From (1.1) the following relations hold

$$\bar{T} = 0 \tag{1.3}$$

$$A(\bar{X}) = 0 \tag{1.4}$$

$$A(T) = 1 \tag{1.5}$$

In addition, if in V^n there exists a metric tensor g satisfying

$$g(FX, FY) = g(X, Y) - A(X)A(Y) \tag{1.6}$$

And
$$g(X.T) = A(X) \tag{1.7}$$

Then V^n is called an almost contact metric manifold.

Let (V^n, g) be an n -dimensional Riemannian manifold of class C^∞ endowed with a Riemannian metric g and let D be the Levi-Civita connection on V^n .

Let \tilde{B} be an linear Connection defined on V^n . The Torsion tensor $S(X, Y)$ at \tilde{B} is given by (Kobayashi and Nomizu 1963).

$$S(X, Y) = \tilde{B}_X Y - \tilde{B}_Y X - [X, Y] \tag{1.8}$$

Where X and Y are arbitrary vector fields if the torsion tensor S is of the form

$$S(X, Y) = A(Y)X - A(X)Y \tag{1.9}$$

Where A is a 1-form, then \tilde{B} is called Semi-Symmetric connection.

The connection \tilde{B} is called a non metric connection if

$$(\tilde{B}_X g) (Y, Z) = 2 A(Y) g(X, Z) + 2 A(Z) g(X, Y) \tag{1.10}$$

It is known that (S. K. Chaubey and R. H. Ojha) for a Semi-Symmetric non metric connection

$$(\tilde{B}_X Y) = D_X Y - A(Y)X - g(X, Y) T \tag{1.11}$$

where T is a vector field satisfying

$$g(X, T) = A(X) \quad \text{for any vector field } X.$$

Sharfuddin and Hussain defined a Semi-Symmetric metric connection in an almost contact manifold by identifying 1-form A at (1.9) with the contact 1-form η . i.e.,

$$S(X, Y) = \eta(Y)X - \eta(X)Y$$

In 1995, Mileva Prvanovic studied a Semi Symmetric metric connection in a locally decomposable Riemannian space whose torsion tensor T satisfies the condition

$$(\tilde{B}_X T) (Y, Z) = A(X) S(Y, Z) + A(FX) F(S(Y, Z)) \tag{1.12}$$

where A is a 1-form and F is a tensor field of type (1.1). In this paper we study a Semi-Symmetric non metric connection on an almost contact metric manifold satisfying (1.10) and

$$(\tilde{B}_X T) (Y, Z) = A(X) S(Y, Z) + A(\phi X) \phi(S(Y, Z)) \tag{1.13}$$

Where ϕ is the tensor field of type (1.1) of the almost contact metric manifold.

2. Definition: Let \tilde{B} be a linear connection defined by

$$\tilde{B}_X Y = D_X Y - A(Y)X - g(X, Y)T$$

where D is a Riemannian connection. Thus a relation between the curvature tensor K and \bar{R} at the connections D and \tilde{B} respectively are given by

$$\begin{aligned} \bar{R}(X, Y, Z) &= K(X, Y, Z) - \beta(X, Z)Y + \beta(Y, Z)X - g(Y, Z)(D_X T - \pi(X)T) \\ &\quad + g(X, Z) (D_Y T - \pi(Y)T) \end{aligned} \tag{2.1}$$

Where
$$\bar{R}(X, Y, Z) = \tilde{B}_X \tilde{B}_Y Z - \tilde{B}_Y \tilde{B}_X Z - \tilde{B}_{[X, Y]} Z \tag{2.2}$$

$$K(X, Y, Z) = D_X D_Y Z - D_Y D_X Z - D_{[X, Y]} Z \tag{2.3}$$

and
$$\beta(Y, Z) \text{ def}^n (D_Y \pi) (Z) + \pi(Y)\pi(Z) + g(Y, Z) \pi(T) \tag{2.4}$$

Where
$$\pi(T) = 1$$

is the curvature tension with Respect to the Riemannian connection D .

The weyl conformal curvature tensor at the manifold is defined by

$$C(X, Y, Z) = R(X, Y, Z) + \alpha(Y, Z)X - \alpha(X, Z)Y - g(Y, Z)LX - g(X, Z)LY \quad 2.5$$

Where
$$\alpha(Y, Z) = g(LX, Z) = \frac{1}{n-2} T(Y, Z) + \frac{r}{2(n-1)(n-2)} g(Y, Z) \quad 2.6$$

T and r denote respectively the $(0, 2)$ Ricci tensor and Scalar curvature of the manifold.

The projective curvature tensor of the manifold is defined by

$$P(X, Y, Z) = R(X, Y, Z) - \frac{1}{n-1} [S(Y, Z)X - S(X, Z)Y] \quad 2.7$$

3. Curvature tensor of a Semi-Symmetric non metric connection:

We have to know that

$$S(Y, Z) = \eta(Z)Y - \eta(Y)Z \quad 3.1$$

Where
$$\eta(Z) = g(Z, \xi) \quad 3.2$$

From (3.1) contracting Y we get

$$(E_1^1 S)(Z) = (n-1) \eta(Z) \quad 3.3$$

Now
$$(\tilde{B}_X E_1^1 S)(Z) = (n-1) (\tilde{B}_X \eta)(Z) \quad 3.4$$

Let
$$(\tilde{B}_X S)(Y, Z) = A(X)S(Y, Z) + A(\phi X) \phi(S(Y, Z)) \quad 3.5$$

Where A is a 1-form and ϕ is a tensor field of typed $(1, 1)$.

Contracting Y the above equation we get

$$(\tilde{B}_X E_1^1 S)(Z) = (n-1) A(X)\eta(Z) + a A(\phi X)\eta(Z) \quad 3.6$$

Where
$$a = (E_1^1 \phi)Y \quad 3.7$$

From (3.4) and (3.6)

$$(\tilde{B}_X \eta)(Z) = A(X)\eta(Z) + bA(\phi X)\eta(Z) \quad 3.8$$

Where
$$b = \frac{a}{n-1} \quad 3.9$$

Using (1.5) we get

$$(\tilde{B}_X \eta)(Z) = (D_X \eta)(Z) - \eta(x)\eta(Z) - g(X, Z) \quad 3.10$$

Using (3.8) and (3.10) we get

$$(D_X \eta)(Z) = A(X)\eta(Z) + bA(\phi X)\eta(Z) + \eta(X)\eta(Z) + g(X, Z) \quad 3.11$$

From (2.4) and (3.11) we get

$$\beta(X, Z) = A(X)\eta(Z) + bA(\phi X)\eta(Z) + 2\{n(X)\eta(Z) + g(X, Z)\} \tag{3.12}$$

Therefore the curvature tensor \bar{R} of the manifold with respect to the Semi-Symmetric non metric connection \tilde{B} is given by

$$\begin{aligned} \bar{R}(X, Y, Z) = & K(X, Y, Z) + g(Y, Z)\{2X - \bar{X} + \pi(X)T\} + g(X, Z)\{\bar{Y} - 2Y - \pi(Y)T\} \\ & - \eta(Z)Y\{A(X) + bA(\phi X) + 2\eta(X)\} + \eta(Z)X\{A(Y) + bA(\phi Y) + 2\eta(Y)\} \end{aligned} \tag{3.13}$$

Where K denotes the curvature tensor of the manifold.

Theorem- 3.1: The curvature tensor with respect to \tilde{B} of an almost contact metric manifold admitting a Semi-Symmetric non metric connection \tilde{B} is

$$\begin{aligned} 'K(X, Y, Z) = & 2\eta(Z)\{\eta(X)g(Y, V) + \eta(Y)g(X, V)\} - A(\xi)\eta(Z) \\ & \{\eta(Y)g(X, V) - \eta(X)g(Y, V)\} - g(Y, Z)\{2\eta(X, V) - g(\bar{X}, V)\} - g(X, Z) \\ & \{g(\bar{Y}, V) - 2g(Y, V)\} - \eta(V)\{g(Y, Z)\pi(X) - g(X, Z)\pi(Y)\} \end{aligned} \tag{3.14}$$

Proof: From (3.13) it is obvious that

$$\bar{R}(X, Y, Z) = -\bar{R}(Y, X, Z) \tag{3.15}$$

We now define a tensor $'\bar{R}$ of the type (0, 4) by

$$'\bar{R}(X, Y, Z, V) = g(\bar{R}(X, Y, Z), V) \tag{3.16}$$

Equation (3.13) and (3.16) we obtain that

$$'\bar{R}(X, Y, Z, V) = -'\bar{R}(Y, X, Z, V) \tag{3.17}$$

Again from (3.13) we get

$$\begin{aligned} \bar{R}(X, Y, Z) + \bar{R}(Y, Z, X) + \bar{R}(Z, X, Y) = & \{A(X) + bA(\phi X) + 2\eta(X)\} \\ & \{\eta(Y)Z - \eta(Z)Y\} + \{A(Y) + bA(\phi Y) + 2\eta(Y)\} \{\eta(Z)X - \eta(X)Z\} \\ & + \{A(Z) + bA(\phi Z) + 2\eta(Z)\} \{\eta(X)Y - \eta(Y)X\} \end{aligned} \tag{3.18}$$

This is the first Bianchi identity with respect to \tilde{B} let \bar{T} and T denote respectively the Ricci tensor of the manifold with respect to \tilde{B} and D

From 3.13 contracting X

$$\begin{aligned} \bar{T}(Y, Z) = & T(Y, Z) + 3(n-1)g(Y, Z) + g(\bar{Y}, Z) + (n-1)A(Y)\eta(Z) \\ & + 2(n-1)\eta(Y)\eta(Z) + (n-1)bA\phi(Y)\eta(Z) \end{aligned} \tag{3.19}$$

$$A(Y) + bA(\phi Y) = A(\eta)\xi(Y)$$

Using the result from (3.18) we get

$$\bar{R}(X, Y, Z) + \bar{R}(Y, Z, X) + \bar{R}(Z, X, Y) = A(\xi)\{\eta(X) + \eta(Y) + \eta(Z)\} \tag{3.26}$$

Conversely we assume that (3.26) holds, then in virtue of (3.18) we have

$$\begin{aligned} & \{A(X) + bA(\phi X) + 2\eta(X)\} \{\eta(Y)Z - \eta(Z)Y\} + \{(A(Y) + bA(\phi Y) + 2\eta(Y))\} \\ & \{\eta(Z)X - \eta(X)Z\} + \{A(Z) + bA(\phi Z) + 2\eta(Z)\} \{\eta(X)Y - \eta(Y)X\} \\ & = A(\xi)\{\eta(X) + \eta(Y) + \eta(Z)\} \end{aligned} \tag{3.27}$$

Contracting X above equation we get

$$\begin{aligned} A(Z)\eta(Y) + bA(\phi Z)\eta(Y) - A(Y) - bA(\phi Y) &= A(Y)\eta(Z) + bA(\phi Y)\eta(Z) \\ &\quad - A(Z) - bA(\phi Z) \end{aligned}$$

Hence by (3.21) \bar{T} is symmetric.

Proved

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