



On the Convergence of A Newly Developed Non-Linear Computational Algorithm

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ABSTRACT

This paper presents a comprehensive detail of the convergence theorem for a newly developed non-linear method for numerical integration of ordinary differential equations. It is proved that the scheme is convergent.

KEYWORDS : Convergence, Numerical integration, ordinary differential equation, computational Algorithm

INTRODUCTION 1.0

We have established the numerical integration algorithm (1.1) which can be expressed as one-step methods in the form:

$$\begin{aligned}
 y_{n+1} = y_n + & \left[\frac{f_n^3 - \lambda f_n^2 + f_n^1 - \lambda f_n}{2(1 - \lambda x_n)} \right] (2n + 1)h^2 + \left[\frac{f_n^2 \cos x_n - f_n^3 \sin x_n}{\lambda^3 (\cos x_n - \lambda \sin x_n)} \right] \left[\sum_{r=1}^{\infty} \frac{(\lambda h)^r}{r!} \right] \\
 & + \left[\frac{f_n^3 - \lambda f_n^2}{\cos x_n - \lambda \sin x_n} \right] \left[\cos x_n \left(\sum_{r=1}^{\infty} \frac{h^{2r}}{2r!} \right) - \sin x_n \left(\sum_{r=0}^{\infty} \frac{h^{2r+1}}{(2r+1)!} \right) \right] \tag{1.1}
 \end{aligned}$$

$$y_{n+1} = y_n + h\phi(x_n, y_n; h)$$

Where

$$\phi(x_n, y_n; h) = \{P f_n + Q f_n^1 + R f_n^2 + S f_n^3\} \tag{1.2}$$

is the increment function.

Definition 1.0 (Henrici, 1962)

We define any algorithm for solving a differential equation in which the approximate the solution at the point x_{n+1} can be calculated if only x_n, y_n and h are known as method. It is a common practice to write the functional dependence, y_{n+1} , on the quantity and h in the form $y_{n+1} = y_n + h\phi(x_n, y_n; h)$.

We observe that $\phi(x_n, y_n; h) = \{P f_n + Q f_n^1 + R f_n^2 + S f_n^3\} \tag{1.3}$

2.0 CONVERGENCE OF THE NON- LINEAR COMPUTATIONAL ALGORITHM

Theorem 1.0 (Henrici, 1962)

$x \in [a, b]$ and $y \in (-\infty, \infty)$; $0 \leq h \leq h_0$, where $h_0 > 0$, and let there exists a constant that $|\Phi(x_n, y_n^*; h) - \Phi(x_n, y_n; h)| \leq L|y_n^* - y_n|$

For all $(x_n, y_n; h)$ and $(x_n, y_n^*; h)$ in the region just define.

Then the relation $(x_n, y_n; 0) = (x_n, y_n)$ is a necessary and sufficient condition convergence of the new scheme defined above in (1.3)

Proof

The increment function $\Phi(x_n, y_n; h)$ can be written in the form:

$$\Phi(x_n, y_n; h) = \{Pf_n + Qf_n^1 + Rf_n^2 + Sf_n^3\} \tag{2.0}$$

Where P, Q, R and S are coefficients defined below:

$$P = -\frac{\lambda(2n+1)}{2(1-\lambda x_n)} h$$

$$Q = \frac{h(2n+1)}{2(1-\lambda x_n)}$$

$$R = \frac{\lambda(2n+1)h}{2(1-\lambda x_n)} + \left(\frac{12 + 6h + 2h^2\lambda^2}{12\lambda^2} - \frac{\lambda h^7 - 56\lambda h^5 - 20160h\lambda}{40320} \right) \frac{\cos x_n}{\cos x_n - \lambda \sin x_n}$$

$$+ \left(\frac{\lambda h^6 - 42\lambda h^4 + 840\lambda h^2 - 210\lambda h^3}{5040} \right) \frac{\sin x_n}{\cos x_n - \lambda \sin x_n}$$

$$S = \frac{2n+1}{2(1-\lambda x_n)} + \left(\frac{(2-h\lambda)}{2\lambda^2} - \frac{210\lambda h^3 - 5040 - 42h^4 - h^6}{5040} \right) \frac{\sin x_n}{\cos x_n - \lambda \sin x_n}$$

$$+ \left(\frac{20160h + 1680h^3 + 56h^5 + h^7}{40320} \right) \frac{\cos x_n}{\cos x_n - \lambda \sin x_n}$$

Equation (2.2), can also be written as,

$$\Phi(x_n, y_n^*; h) = \{Pf(x, y_n^*) + Qf^1(x, y_n^*) + Rf^2(x, y_n^*) + Sf^3(x, y_n^*)\} \tag{2.1}$$

Subtract (2.0) from (2.1), hence:

$$\phi(x_n, y_n^*; h) - \phi(x_n, y_n; h) = \left\{ \begin{array}{l} P(f(x, y_n^*) - f(x, y_n)) + Q(f^1(x, y_n^*) - f^1(x, y_n)) \\ +R(f^2(x, y_n^*) - f^2(x, y_n)) + S(f^3(x, y_n^*) - f^3(x, y_n)) \end{array} \right\}$$

Let \bar{y} be defined as a point in the interior of the interval whose points are y and y^* , applying mean value theorem, we have:

$$\left. \begin{array}{l} f(x_n, y_n^*) - f(x_n, y_n) = \frac{\partial f(x_n, \bar{y})}{\partial y_n} (y_n^* - y_n) \\ f'(x_n, y_n^*) - f'(x_n, y_n) = \frac{\partial f'(x_n, \bar{y})}{\partial y_n} (y_n^* - y_n) \\ f^2(x_n, y_n^*) - f^2(x_n, y_n) = \frac{\partial f^2(x_n, \bar{y})}{\partial y_n} (y_n^* - y_n) \\ f^3(x_n, y_n^*) - f^3(x_n, y_n) = \frac{\partial f^3(x_n, \bar{y})}{\partial y_n} (y_n^* - y_n) \end{array} \right\} \quad 2.2$$

$$\left. \begin{array}{l} L = \sup_{(x_n, y_n) \in D} \frac{\partial f(x_n, y_n)}{\partial y_n} \\ L_1 = \sup_{(x_n, y_n) \in D} \frac{\partial f'(x_n, y_n)}{\partial y_n} \\ L_2 = \sup_{(x_n, y_n) \in D} \frac{\partial f^2(x_n, y_n)}{\partial y_n} \\ L_3 = \sup_{(x_n, y_n) \in D} \frac{\partial f^3(x_n, y_n)}{\partial y_n} \end{array} \right\} \quad 2.3$$

Therefore

$$\begin{aligned} \phi(x_n, y_n^*; h) - \phi(x_n, y_n; h) &= P \left\{ \frac{\partial f(x_n, \bar{y})}{\partial y_n} (y_n^* - y_n) \right\} + Q \left\{ \frac{\partial f'(x_n, \bar{y})}{\partial y_n} (y_n^* - y_n) \right\} \\ &\quad + R \left\{ \frac{\partial f^2(x_n, \bar{y})}{\partial y_n} (y_n^* - y_n) \right\} + S \left\{ \frac{\partial f^3(x_n, \bar{y})}{\partial y_n} (y_n^* - y_n) \right\} \\ &= PL(y_n^* - y_n) + Q L_1(y_n^* - y_n) + R L_2(y_n^* - y_n) + S L_3(y_n^* - y_n) \end{aligned} \quad 2.4$$

Taking the absolute value of both sides

$$|\phi(x_n, y_n^*; h) - \phi(x_n, y_n; h)| \leq |PL + Q L_1 + R L_2 + S L_3| |y_n^* - y_n| \quad 2.5$$

If we let $M = |PL + Q L_1 + R L_2 + S L_3|$ then, our equation (2.5) becomes

$$|\phi(x_n, y_n^*; h) - \phi(x_n, y_n; h)| \leq M |y_n^* - y_n| \quad 2.6$$

which is the condition for convergence.

3.0 CONSISTENCE OF THE NON-LINEAR COMPUTATIONAL ALGORITHM

Definition 2.0 (Fatunla, 1988)

A numerical scheme with an increment function $\emptyset(x_n, y_n; h)$ is said to

be consistent with the initial value problem

$$y' = f(x, y); \quad y(x_0) = y_0 \tag{3.0}$$

From (1.2), $y_{n+1} = y_n + h\emptyset(x_n, y_n; h)$

Where

$$\emptyset(x_n, y_n; h) = \{Pf_n + Qf_n^1 + Rf_n^2 + Sf_n^3\} \tag{3.1}$$

If $h = 0$, then

$$y_{n+1} = y_n + \left[\frac{f_n^3 - \lambda f_n^2 + f_n^1 - \lambda f_n}{2(1-\lambda x_n)} \right] (2n + 1)h^2 + \left[\frac{f_n^2 \cos x_n - f_n^3 \sin x_n}{\lambda^3 (\cos x_n - \lambda \sin x_n)} \right] \left[\sum_{r=1}^{\infty} \frac{(\lambda h)^r}{r!} \right]$$

$$+ \left[\frac{f_n^3 - \lambda f_n^2}{\cos x_n - \lambda \sin x_n} \right] \left[\cos x_n \left(\sum_{r=1}^{\infty} \frac{h^{2r}}{2r!} \right) - \sin x_n \left(\sum_{r=0}^{\infty} \frac{h^{2r+1}}{(2r+1)!} \right) \right]$$

Becomes

$y_{n+1} = y_n$, hence

$$\emptyset(x_n, y_n; 0) = f(x, y) \tag{3.2}$$

Therefore a consistent method has order of at least one. We say our new numerical method is consistent since equation (2.5) reduces to (3.2) when $h = 0$, therefore, we say that the method is consistent

4.0 STABILITY ANALYSIS OF THE NON-LINEAR COMPUTATIONAL ALGORITHM

THEOREM 2.0 (Fatunla, 1988)

Let $y_n = y(x_n)$ and $p_n = p(x_n)$ denote two different numerical solution of differential equation (3.0) with the initial conditions specified as

$$y(x_0) = \zeta \text{ and } p(x_0) = \zeta^* \text{ respectively, such that } |\zeta - \zeta^*| < \varepsilon, \quad \varepsilon > 0.$$

If the two numerical estimates are generated by the integration scheme, we have:

$$y_{n+1} = y_n + h\phi(x_n, y_n; h) \tag{4.0}$$

$$p_{n+1} = p_n + h\phi(x_n, p_n; h) \tag{4.1}$$

The condition that

$$|y_{n+1} - p_{n+1}| \leq k|\zeta - \zeta^*|$$

Is the necessary and sufficient condition that our new method is stable and convergent.

Proof:

$$\text{If } y_{n+1} = y_n + h\{Pf_n + Qf_n^1 + Rf_n^2 + Sf_n^3\} \tag{4.2}$$

Then let

$$y_{n+1} = y_n + h\{Pf(x_n, y_n) + Qf^1(x_n, y_n) + Rf^2(x_n, y_n) + Sf^3(x_n, y_n)\} \tag{4.3}$$

And

$$p_{n+1} = p_n + h\{Pf(x_n, p_n) + Qf^1(x_n, p_n) + Rf^2(x_n, p_n) + Sf^3(x_n, p_n)\} \tag{4.4}$$

Therefore

$$y_{n+1} - p_{n+1} = y_n - p_n + h \left\{ \begin{array}{l} P(f(x_n, y_n) - f(x_n, p_n)) \\ + Q(f^1(x_n, y_n) - f^1(x_n, p_n)) \\ + R(f^2(x_n, y_n) - f^2(x_n, p_n)) \\ + S(f^3(x_n, y_n) - f^3(x_n, p_n)) \end{array} \right\} \tag{4.5}$$

Applying the mean value theorem, we have as above:

$$y_{n+1} - P_{n+1} = y_n - P_n + h \left\{ \begin{array}{l} \frac{P\partial f(x_n, P_n)}{\partial P_n}(x_n - P_n) \\ + \frac{Q\partial f^1(x_n, P_n)}{\partial P_n}(x_n - P_n) \\ + \frac{R\partial f^2(x_n, P_n)}{\partial P_n}(x_n - P_n) \\ + \frac{S\partial f^3(x_n, P_n)}{\partial P_n}(x_n - P_n) \end{array} \right\} \tag{4.6}$$

$$y_{n+1} - P_{n+1} = y_n - P_n$$

$$+h \left\{ \begin{array}{l} \sup_{(x_n, P_n) \in D} \frac{P\partial f(x_n, P_n)}{\partial P_n}(x_n - P_n) \\ + \sup_{(x_n, P_n) \in D} \frac{Q\partial f^1(x_n, P_n)}{\partial P_n}(x_n - P_n) \\ + \sup_{(x_n, P_n) \in D} \frac{R\partial f^2(x_n, P_n)}{\partial P_n}(x_n - P_n) \\ + \sup_{(x_n, P_n) \in D} \frac{S\partial f^3(x_n, P_n)}{\partial P_n}(x_n - P_n) \end{array} \right\} \tag{4.7}$$

$$y_{n+1} - p_{n+1} = y_n - p_n + h \left\{ \begin{array}{l} PL(x_n, p_n) \\ + QL_1(x_n, p_n) \\ + PL_2(x_n, p_n) \\ + SL_3(x_n, p_n) \end{array} \right\} \tag{4.8}$$

Taking the absolute value of both sides of (4.8) gives

$$|y_{n+1} - p_{n+1}| \leq |y_n - p_n| + h|PL + Q L_1 + R L_2 + S L_3||x_n - p_n| \tag{4.9}$$

$$\text{let } N = |PL + Q L_1 + R L_2 + S L_3|$$

and $y(x_0) = \zeta$ and $p(x_0) = \zeta^*$, given $\varepsilon > 0$. Then

$$|y_{n+1} - p_{n+1}| \leq N|y_n - p_n| \tag{4.10}$$

And

$$|y_{n+1} - p_{n+1}| \leq N|\zeta - \zeta^*| \text{ for every } \varepsilon > 0 \quad 4.11$$

Then we conclude that our scheme is stable and hence convergent.

5.0 CONCLUSION AND RECOMMENDATION; we have presented comprehensive detail of the convergence theorem for a newly developed non-linear method for numerical integration of ordinary differential equations. It is proved that the scheme is convergent.

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