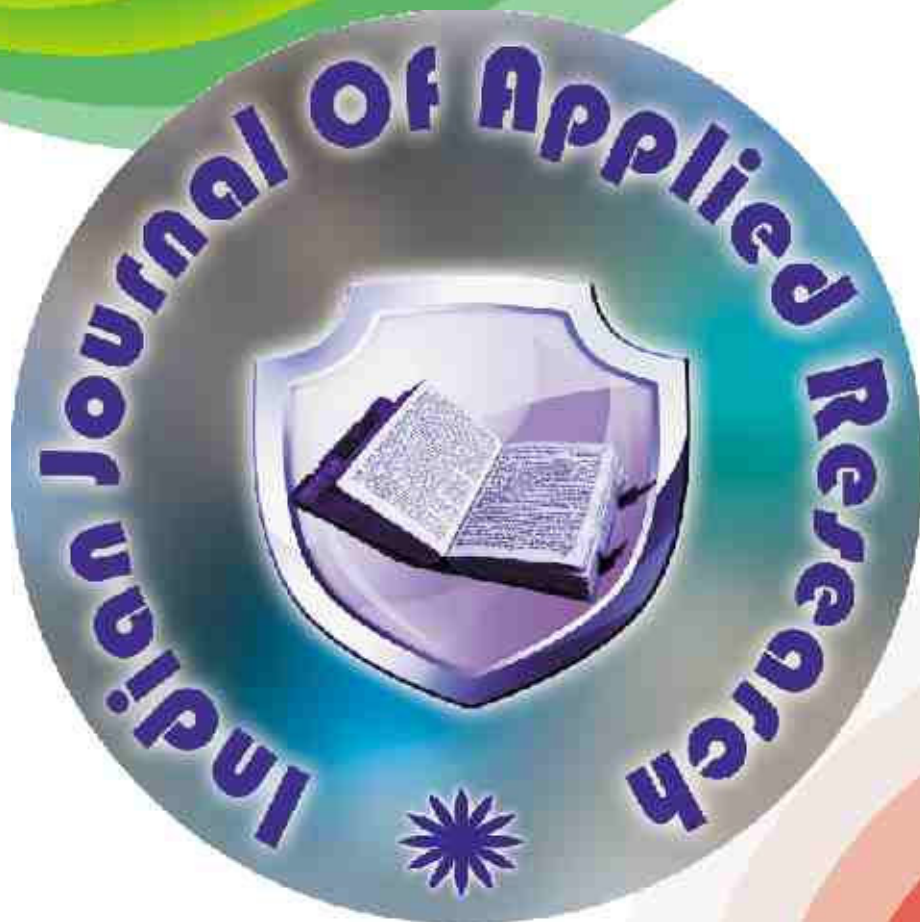


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INDEX

Sr. No	Title	Author	Subject	Page. No.
1.	Statistical Optimization Of Ferulic Acid Esterase Production In Aspergillus Niger Isolate Using Response Surface Methodology	Balljinder Kaur , Neena Garg	Biotechnology	1-6
2.	Development Of Forest Area In Tropics: The Urgency Of People's Participation In The Indian Context	Dr. M. P. Naik	Commerce	7-8
3.	Opportunity For International Corporations At Bop Segments Of Emerging Markets (Focus : India)	Bhudhar Ranjan Chatterjee , Sukanya Chatterjee.	Commerce	9-11
4.	Retail Trade	Viram. J. Vala , Dr. (Prof.) Vijay Kumar Soni	Commerce	12-15
5.	Determinants Of Market Value Added Some Empirical Evidence From Indian Automobile Industry	Dr. A. Vijayakumar	Commerce	16-20
6.	The Welfare Facilities Available To The Workers In Paper Mills In Madurai	Dr. M. Sumathy , A. Vijayalekshmi	Commerce	21-24
7.	Green Marketing - New Hopes And Challenges	Dr. Prashant M. Joshi	Commerce	25-27
8.	A Study On Employee Welfare Measures In Maharashtra State Transport Corporation With Special Reference To Kolhapur District.	Dr. H. M. Thakar , Prof. Urmila Kisan Dubal	Commerce	28-30
9.	Business Environment In South Korea An International Perspective	Dr. M. Kamalun Nabi , Dr. M. Saeed	Commerce	31-35
10.	Market Timing - Implications Of Market Valuation On Share Issues By Indian Companies	L. Ganesamoorthy , Dr. H. Shankar	Commerce	36-38
11.	The Conceptual Framework Of Corporate Social Accounting	Rechanna , Dr. B. Mahadevappa	Commerce	39-50
12.	Labour Welfare Measures And The Extent Of Satisfaction Of Tirupur Garment Employees	Mr. S. Hariharan , Mr. N. Selvakumar, Dr .H. Balakrishnan	Commerce	51-53
13.	Mahila Savstha Aur Jacha-Bacha Ko Bachane Ko Chunoti	Dr. Anup Chaturvedi	Community Science	54-55
14.	Mapping Of Existing Waste Dumping Sites And Newly Proposed Waste Dumping Sites In And Around Chitradurga Taluk, Karnataka State, Using Remote Sensing And GIS Techniques.	Sunil Kumar R. K Chinnaiiah , Suresh Kumar B.V	Earth Science	56-58
15.	A Role Of Municipal Council And Corporation Of Financial Problems In Nanded District (Maharashtra)	Dr. A. S. Pawar	Economics	59
16.	Impact Of Institutional Credit On Weaker Section In Akola District	Dr. Devyanee K Nemade, Dr. Vanita K Khobarkar	Economics	60-62
17.	Right To Education In India	Dr. Pawar A. S.	Economics	63-65
18.	Gramin Ayam Adivasi Mahilo Ke Arthik Shakti : Sukhma Virti (Adipur Jila Ke Gramin Ayam Adivasi Mahilao Ka Ek Ayaktik Adhiyan Shobha Gupta	Shobha Gupta	Economics	66-67

19.	Knowledge On Food Security Education Among Higher Secondary Students	Dr. P. Paul Devanesan , Dr. A. Selvan	Education	68-69
20.	Family Environment As A Determinant of Academic Anxiety And Academic Achievement	Dr. RajKumari Kalra , Ms. Preeti Manani	Education	70-71
21.	Awareness On Man-Made Disaster In Environmental Education Among High School Students	Dr. A. Selvan , Dr. P. Paul Devanesan	Education	72-73
22.	Teaching Strategies For Simplifying Fractions In Mathematics	M. Kavitha , Dr. A R. Saravanakumar	Education	74-76
23.	Mahatma Gandhi National Rural Employment Guarantee Scheme (MGNREGA): A Boon to Tribal Women	Dr. Sherly Thomas	Education	77-78
24.	Sports as a Tool for Interest Oriented Learning	E. Baby Sumanna	Education	79-80
25.	Balanced Scorecard for Higher Education	Jyoti D Joshi	Education	81-83
26.	A Study Of The Interactive Influence Of CAI Package On Academic Achievement	Kunal D. Jadhav	Education	84-85
27.	Reduction Of Fault Current Using SFCL At The Suitable Location In The Smartgrid	Pudi Sekhar , K .Venkateswara Rao , M. Ebraheem , P. Nageswara Rao	Electronics	86-88
28.	HRD Climate in Private Manufacturing Sector: An Appraisal	Dr. Sukhwinder Singh Jolly	Engineering	89-90
29.	Wireless Speed Measurement And Control Of Universal Motor	G. Prasad , G. Ramya Swathi, Dr. P. V. N. Prasad , A. Muneiah	Engineering	91-94
30.	Design Of Decentralized Load-Frequency Controller For Deregulated Hydro-Thermal Power Systems With Non-Linearities	M. Vinothkumar , Dr. C. Kumar , Dr. S. Velusami	Engineering	95-99
31.	Optimization Of Process Parameters For Gas Tungsten Arc Welding Aluminum Alloy A6061 By Taguchi Method	P. Hema , K. Allama Prabhu , Prof. K. Ravindranath	Engineering	100-103
32.	Numerical Approach To Predict The Thermal Performance Of Parallel And Counter Flow Packed Bed Solar Air Heaters	Satyender Singha , Prashant Dhiman , Ritika Kondal	Engineering	104-108
33.	Institute For Entrepreneurship Development Amongst Farmers- Especially Small And Marginal Land Holders.	Sweta Sanjog Metha	Entrepreneurship Development	109-111
34.	Phytoplankton Diversity From Godavari River Water (Maharashtra)	Satish.S.Patil , Ishwar.B.Ghorade	Environmental Science	11-114
35.	Nutrient Adequacy Among Selected Tribal Adolescent Girls Of Kattunayakan Tribes In Tamil Nadu	Somishon Keishing , Saranya .R	Home Science	115-116
36.	Vaigyanic Sacharata Aur Arthik- Samajik Vikas	Dr. Sudobh Kumar	Humanities	117-118
37.	E-Pharmacy In India For Reducing Inter-State Accessibility Dispersion	Satinder Bhatia	Information Technology	119-121
38.	Impact Of Intermediaries' Service Delivery In Insurance Sector	Dr. P. Anbuoli , R. Meikanda Ganesh Kumar	Insurance Sector	122-124

39.	Fate And Human Endeavour In The Mahabharata	Dr Maneeta Kahlon	Literature	125-127
40.	Facets of Hunger in Bhabani Bhattacharya's So Many Hungers and Kamala Markandaya's Nectar in a Sieve	Dr. Paramleen Kaur Syali , Ruchee Aggarwal	Literature	128-129
41.	Business Financial Strategy In Small And Medium Scale Brick Industries In Kolar District, Karnataka State.	Muninarayanappa , Dr. S. Muralidhar	Management	130-132
42.	A Study On Brand Equity Analysis Foreign Global Brands Vs Domestic Popular Brands Of Adult Consumer's Perspective In Coimbatore City	A.Pughazhendi , S. Susendiran , R. Thirunavukkarasu	Management	133-135
43.	Comparative Analysis of Cellular Phone Usage Outline of Undergraduate Students.	Atul Patel	Management	136-138
44.	A Study On Management Practices Of Entrepreneurs In Informal Sector	Dr. P. Vikkraman , Mr. S. Baskaran	Management	139-142
45.	E-commerce: Emerging Channel for Marketing in India	Dr Mahalaxmi Krishnan	Management	143-144
46.	The Role Of Educational Institutions In Imparting Entrepreneurship Qualities Among Student Community	Dr. N. Ramanjaneyalu	Management	145-147
47.	Impulsive buying and In-store shopping environment	Dr. Surekha Rana , Jyoti Tirthani	Management	148-149
48.	A Study On Management Practices Of Entrepreneurs In Informal Sector	Dr. P. Vikkraman , S. Baskaran	Management	150-153
49.	Risk Management Processes And Techniques For Resolving Customer - Supplier Relationship Issues	Pramod Kumar , Prof (Dr.) S.L.Gupta	Management	154-160
50.	Risk Management Processes & Techniques For The Successful Delivery Of Web Based Software Projects	Pramod Kumar , Prof (Dr.) S. L. Gupta	Management	161-166
51.	Effect Of Brand Equity On Consumer Purchasing Behaviour On Car: Evidence From Car Owners In Madurai District	R. Suganya	Management	167-169
52.	Relationship Management Model For Global It Industry.	Rishi Mohan Bhatnagar , Prof (Dr.) S. L. Gupta	Management	170-173
53.	It's A Myth That Kirana Stores Will Be Wiped Out If FDI Is Allowed In Multi Brand Retail Sector In India	Shweta Patel , M R Brahmachari	Management	174-176
54.	Learning Organization	Sitheswaran K , Dr. K. Balanaga Gurunathan	Management	177-178
55.	Behavior Management: A Ready-made Soup For Indian Managers	Winnie Jasraj Joshi	Management	179-180
56.	Customer Relationship Management In Public Sector Banks	Dr. P. Anbuoli , T. R. Thiruvén Kat Raj	Marketing	181-182
57.	Nifedipine Compared With Isoxuprine In Treatment Of Preterm Labor	Dr. Santosh Khajotia	Medical Science	183-184

58.	Single Intraoperative Dose of Tranexamic Acid In Orthopedic Surgery (A Study of Bipolar Modular Prosthesis and Dynamic Hip Screw fixation)	Dr. B. L. Khajotia , Dr. S. K. Agarwal, Dr. Prasant Gadwal	Medical Science	185-187
59.	MVA - A Simple & Safe Surgical Procedure For First Trimester Abortion / Medical Termination Of Pregnancy (MTP)	Dr. Priyamvada Shah , Dr. Sameer Darawade	Medical Science	188-190
60.	Pneumococcal Septic Arthritis in an Infant A Case Report	Dr. Vrishali A Muley , Dr. Dnyaneshwari P Ghadage, . Dr. Arvind V Bhore	Medical Science	191-192
61.	A Clear CSF may not be a Normal CSF A Case Report	Dr. Dnyaneshwari P Ghadage , Dr. Vrishali A. Muley , Dr. Arvind V. Bhore	Medical Science	193-194
62.	Neurectomy For Tic How Much Reliable?	Dr. Monali H. Ghodke , Dr. Seemit V. Shah , Dr. Smita A. Kamtane	Medical Science	195-198
63.	To Assess Acceptability Of Female Condom As A Method Of Temporary Contraception Among Indian Women	Dr Priyanka Shekhawat , Dr. Col (Retd) Gulab Singh, Dr Vidula Kulkarni Joshi	Medical Science	199-200
64.	A Study To Evaluate The Efficacy Of Teaching Intervention On Reduction Of Pediatric Immunization Pain Among Nursing Students	Dr. Ramachandra , Dr. S. Valliammal, Mr. Raja Sudhakar	Nursing	201-202
65.	Screening Of Antenatal Patients For Thalassemia	Dr Mukta Rayate , Dr Durga Karne , Dr Shilpa Bhat, Dr Hemant Damle , Dr Sameer Darawade, Varsha Gogavale	Obstetrics & Gynaecology	203-204
66.	Reservoir Rock Quality of the Lakadong Member in the Eastern Part of Upper Assam Basin, India	Dr. Pradip Borgohain	Petroleum Geology	205-207
67.	Study Of Refractive Index And Excess Parameters For Different Liquid Mixtures At Different Temperatures	Sheeraz Akbar , Mahendra Kumar	Physics	208-210
68.	Refractometric And Excess Parameter Study For Liquid Mixtures Containing High Order Alkanes (C17) And 1-alkanols At Different Temperatures	Sheeraz Akbar , Mahendra Kumar	Physics	211-213
69.	Assessment Of Knowledge About Health Services Available At Subcentre Level Among Village Inhabitants	Balpreet Singh , Jayanti Dutta	Public Health	214-215
70.	Effect Of Yogic, Aerobic And Laughter Exercises On Body Composition (An experimental study)	Dr. Manjappa. P. , Dr. Shivarama Reddy. M	Sports	216-220
71.	Age At Menarche In Physically Active And Non Active Urban Girls Of Patiala District	Jyoti Sharma , Dr. Ajita	Sports Science	221-222
72.	Use Of Ranks For Analysis Of Groups Of Experiments	Dr. Vanita K Khobarkar , Dr. S. W. Jahagirdar, Dr. N. A. Chaube	Statistics	223-225



Wireless Speed Measurement And Control Of Universal Motor

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ABSTRACT

This paper illustrates the speed measurement and control of Universal Motor by using Microcontroller. The setup consists of two units Motor & Power Control Unit and Remote Control Unit. Motor & Power control unit consists of Universal Motor, Speed sensor, Microcontroller and the other components. Similarly Remote control Unit consists of LCD display, Microcontroller, Keypad etc. The system continuously monitors the speed variation of Universal Motor by a Microcontroller and corrects it according to the set speed using a PID algorithm, written in 8051 assembly language. The usage of Microcontroller provides greater flexibility on the operation of the system.

Keywords : Wireless, Motor, Microcontroller, LCD Display, Keypad.

Introduction

The industries need to control the process parameters like Temperature, Speed, Flow etc [1]. accurately. The PID controllers are capable of controlling the process more accurately and also take very less time to correct the process deviations. Modern electronics play a vital role in modeling the instrumentation systems. Wireless [2] speed measurement and control of Universal Motor [3] is one such illustration. The remote wireless setup enables the user to avoid long wires from the probe to the control station and the possibility of short circuit due to cables. Remaining cables between sensor and control are not required which ultimately reduce the error due to unwanted noise signals. Using Microcontroller [4] provides greater flexibility on the operation of the system.

The Wireless Speed Measurement and Control of Universal Motor utilizes 315 MHz VHF carrier, which is approved by government body for a short range wireless communication [2], [5]. This system does not interfere with the other industrial gadgets. It is also immune to celestial noise developed in the harsh environment. The system continuously monitors the speed variation by a Microcontroller and corrects it according to the set speed using a PID algorithm, written in 8051 assembly language.

The present work deals with the hardware setup of motor & power control unit and remote control unit. Which find its key applications in military, agricultural and industrial sectors. The advantages of this unit can be drawn in terms of cost, accuracy in speed and reduction in the error due to unwanted noise signals.

Wireless Speed Measurement And Control

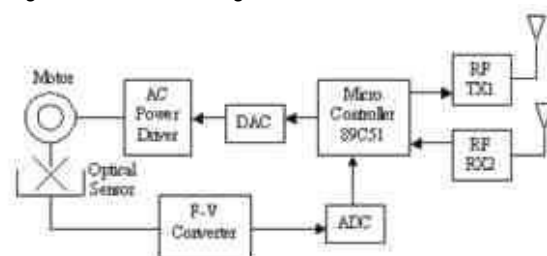
The work aims at controlling and measuring the speed of Universal Motor by implementing PID logic control algorithm

with wireless RF (Radio Frequency) interface. The work comprises of Motor & Power Control Unit and Remote Control Unit. The Motor & Power Control unit consists the following components Motor setup, Optical Sensor, AC Power Driver [6], DAC [7] (Digital to Analog converter), Microcontroller [4], ADC [7] (Analog to Digital converter), F-V (Frequency to voltage) Converter [8] & RF (Transmitter 1 & Receiver 2 Module) [8] while the Remote Control Unit consists of Microcontroller [4], LCD Display [9], keypad & another RF (Transmitter 2 & Receiver 1 Module)[8].

A. Motor & Power Control unit

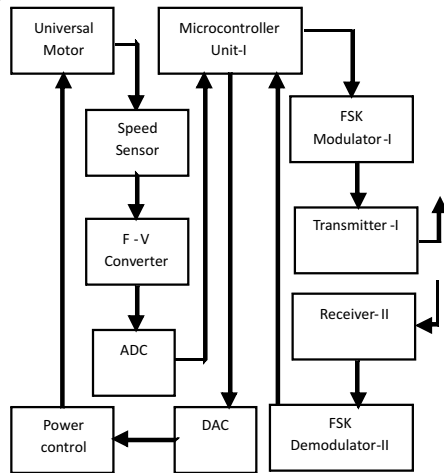
Fig. 1 shows the basic block diagram of Motor & Power Control Unit and fig. 2 shows detailed block diagram of Motor & Power Control Unit.

Figure 1 Basic Block diagram of Motor & Power Control Unit



A Universal Motor is a relatively small series motor specially designed to operate at approximately the same speed and output power on either DC or single phase AC at a frequency of 60 Hz / 50 Hz, and an rms voltage i.e. approximately equal to the DC voltage.

Figure 2 Detailed Block Diagram of Motor & Power Control Unit



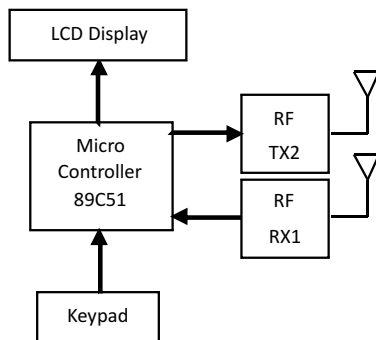
The speed of the Universal Motor is sensed using an optical pick-up sensor. One fan leaf is fixed in the shaft, which cuts the infra-red lights passed to the phototransistor so that it gives a square wave output. The F-V converter block converts the frequency into dc voltage signal. The ADC converts the analog input voltage into digital value. The Microcontroller reads the digital value from ADC and converts into serial format. This serial data is sent to FSK modulator [10] from where the output is transmitted with 315 MHz carrier frequency through RF (Radio Frequency) Transmitter 1 (RF TX 1) module.

The RF Receiver 2 (RF RX 2) module, which demodulates the signal, receives the signal and the data is fed to the Microcontroller. The Microcontroller sends the data to the DAC for Digital to Analog conversion and the output is given to the AC power control Driver. This section controls the AC output given to the motor depend upon the speed settings.

B. Remote Control Unit

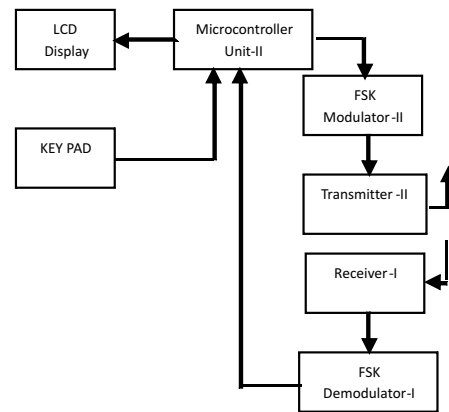
Fig. 3 shows the basic block diagram of Remote Control Unit and fig. 4 shows detailed block diagram of Remote Control Unit.

Fig. 3 Basic Block diagram of Remote Control Unit



The transmitted RF signal is received in the receiver end by RF Receiver (RF RX 1) module. This RF module demodulates [10] the carrier and reproduces the original signal. Another Microcontroller in the receiver end reads this signal and the value is displayed in the LCD display [9]. The user can also change the set point (i.e. speed of the motor can be incremented / decremented) using keypad. The same Microcontroller again reads the value changed by the user and it is transmitted through another RF Transmitter2 module. This module has 433 MHz carrier frequency.

Fig. 4 Detailed Block Diagram of Remote Control Unit



Hardware Implementation

The hardware setup of Motor & Power Control Unit is shown in fig. 5. This hardware setup consists of following components Universal Motor, Optical sensor, F-V converter, ADC [7], Microcontroller [4], FSK modulator [10], FSK demodulator [10], Transmitter, Receiver, DAC [7], AC Power Driver [6].



Fig. 5 Motor & Power Control Unit

The hardware setup of Remote Control Unit is shown in fig. 6. This hardware setup consists of following components Microcontroller [4], LCD display [9], keypad, FSK modulator [10], FSK demodulator [10], Transmitter, Receiver



Fig. 6 Remote Control Unit

Programming Flowcharts

A. Flowchart of Motor & Power Control Unit

The Flowchart of Motor & Power Control Unit enables to visualize the initialization and configuration of Serial Port Baud, 32-byte data array with the aid of 2 pointers, and transmitting the default values to Remote control Unit. It also emphasis on the reset values of the speed transmitted in turn from the Remote control unit to Motor & Power Control unit and thus function according to the new set values. This procedure is reproduced in a schematic diagrammatic representation of the flowchart as shown in fig. 7.

B. Flowchart of Remote Control Unit

The Flowchart of Remote Control Unit enables to visualize the initialization and configuration of Serial Port Baud, LCD, 32-byte data array with the aid of 2 pointers, and display of LCD. The following is the diagrammatic representation of the flow cart as shown in fig. 8.

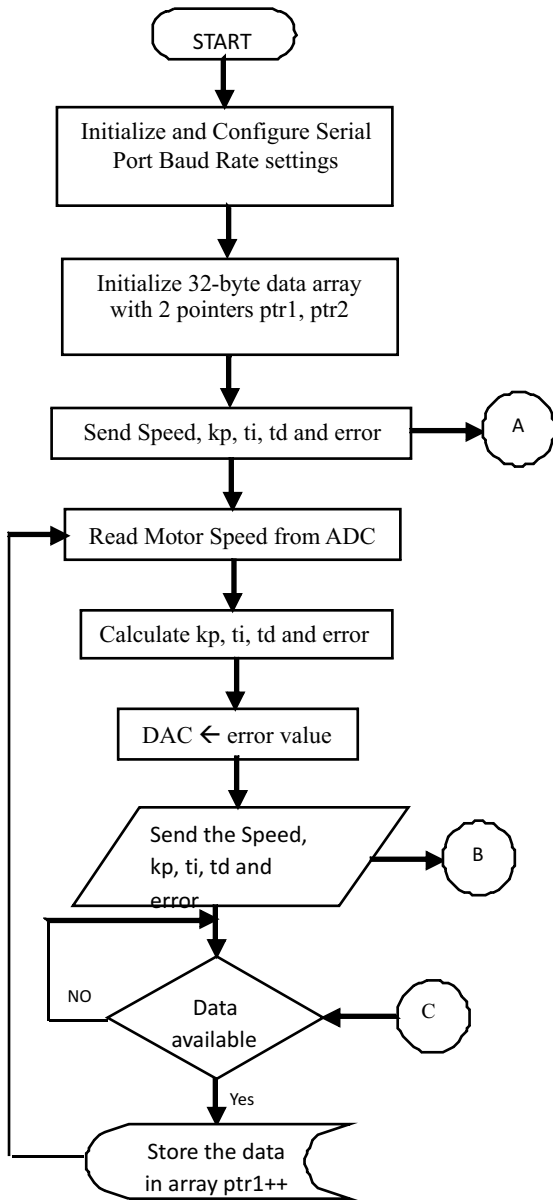


Fig. 7 Flowchart of Motor & Power Control Unit

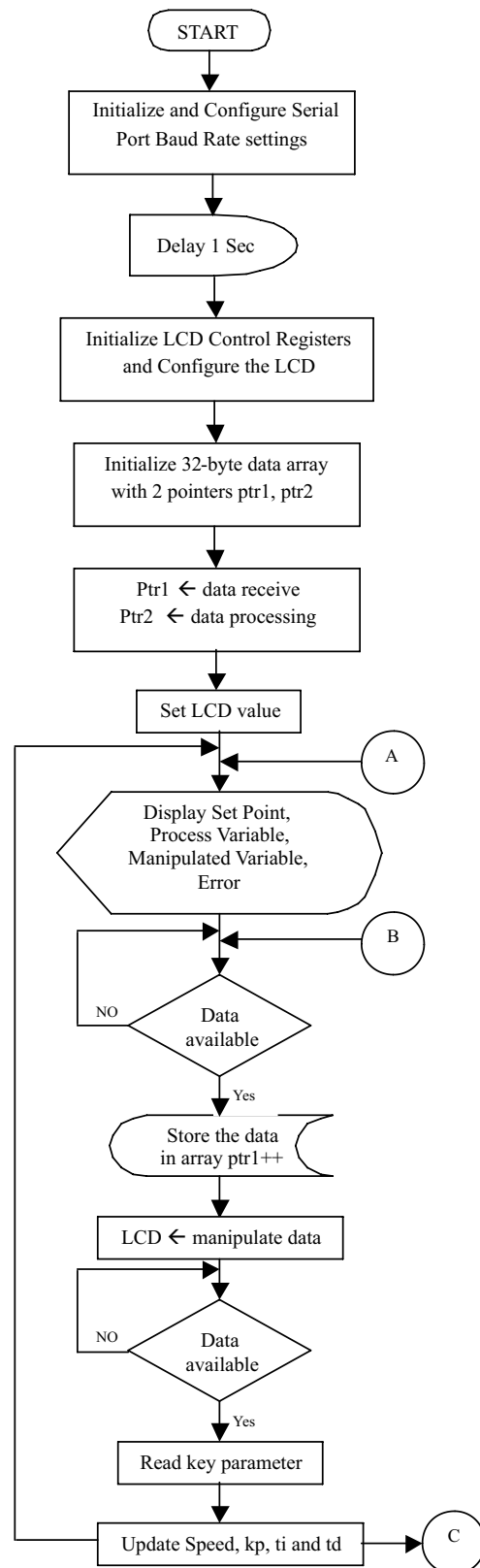


Fig. 8 Flowchart of Remote Control Unit

Result

The following are the experimental results observed when the Motor & Power Control unit and Remote Control unit are setup and the results of the various speeds, current and voltage values are tabulated in Table I. and the corresponding characteristics of the results are graphically represented in Fig. 9.

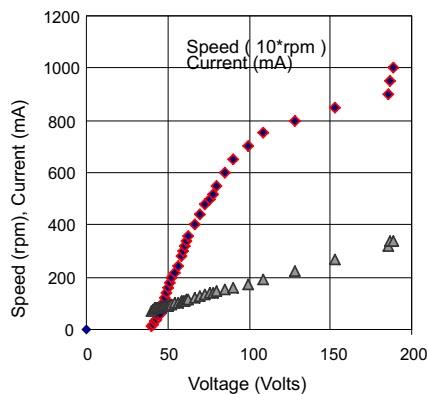
Graphical representation of the results was done by plotting Speed versus Voltage (y-axis depicting Speed and x-axis depicting Voltage); and Current versus Voltage (y-axis depicting Current and x-axis depicting Voltage).

In the Speed versus voltage curve the speed represented on the y-axis is one-tenth (1/10th) of the actual speed in 'rpm'. Similarly, x-axis is the actual values of the Voltage in 'volts'.

In the Current versus voltage curve the current represented on the y-axis is the actual current in mA. Similarly, x-axis represents the actual values of the Voltage in 'volts'.

It can be observed that the variation of speed with voltage is linear while the variation of current is non-linear.

Fig.9 Characteristics of Universal Motor



Conclusion

This work involves the speed measurement and control of Universal Motor by using Microcontroller. The project illustrates basically two units 'Motor & Power Control Unit' and 'Remote Control Unit'. The system continuously monitors the speed variation of Universal Motor by a Microcontroller and corrects it according to the set speed using a PID algorithm, written in 8051 assembly language, which provides satisfactory results for the prescribed job assigned. The key principle of this project is increasing the efficiency, accuracy by reduction of wires and the usage of Remote sensing technology. This remote wireless setup enables the user to avoid long wires from the probe to the control station and the possibility of short circuit due to cables. Remaining cables between sensor and control are not required which ultimately reduces the error due to unwanted noise signals. The usage of Microcontroller in Motor & Power Control Unit and Remote Control Unit provides a greater flexibility on the operation of the system.

Table I

Speed (rpm)	Voltage (Volts)	Current (mA)
0	0	0
100	40	71
200	41	75
300	42	80
400	43	83
500	44	84
600	45	85
800	46	86
1000	47	88
1200	48	89
1400	49	90
1600	50	92
1800	51	93
2000	52	97
2200	54	100
2400	56	105
2800	58	106
3000	59	109
3200	60	110
3400	62	113
3600	63	116
4000	67	123
4400	70	128
4800	73	134
5000	76	138
5200	78	140
5500	80	145
6000	85	152
6500	90	162
7000	99	175
7500	109	190
8000	128	222
8500	153	268
9000	186	318
9500	187	338
10000	189	340

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