



# Single Phase Dual Full Bridge Bi-directional DC-DC Converter for High power applications

**KEYWORDS**

Bi-directional dc-dc converter, galvanic isolation, loss analysis, charger, dis-charger, EDLC

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**ABSTRACT**

This paper presents a bi-directional dc-dc converter for use in high power applications implementing dual operation of full bridge dc-dc converter. The proposed topology has two single phase full bridge converters on either side of the isolation transformer considering EDLC as energy storage device. Typical applications of this scheme are auxiliary power supply in fuel cell vehicles and battery charging/dis-charging systems providing high efficiency, high power density and galvanic isolation. The overall efficiency from dc input to dc output terminals is accurately measured and loss analysis is carried out to estimate effectiveness of power switching devices. Moreover, the dc-dc converter can charge the capacitor bank from zero to rated voltage without any external pre-charging circuit.

**I. INTRODUCTION**

Generally, electric power generated by renewable energy sources is unstable in nature, thus producing a bad effect on the utility grid. This fact spurs research on energy storage systems to smooth out active-power flow on the utility grid. Fig. 1 shows a simplified existing energy storage system employing a line-frequency (50- or 60-Hz) transformer, a PWM converter, a bidirectional chopper, and an energy storage device such as electric double layer capacitors (EDLCs) or lithium-ion batteries. The transformer is indispensable for some applications that require voltage matching and/or galvanic isolation between the utility grid and the energy storage device. Replacing the line-frequency transformer with a high-frequency isolated dc-dc converter would make the energy storage system more compact and flexible.

Various bidirectional isolated dc-dc converters have been proposed as the interface to energy storage devices with focus on automotive or fuel cell applications. Most of the presented dc-dc converters have asymmetrical circuit configurations to couple the two dc links having largely different voltages, several tens of volts and several hundred volts.

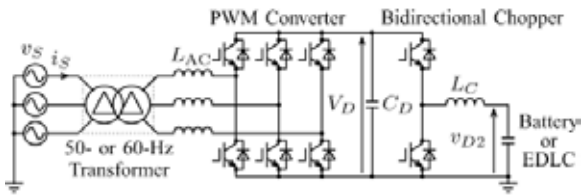


Fig.1. Existing energy storage system employing a 50- or 60-Hz transformer for voltage matching and/or galvanic isolation.

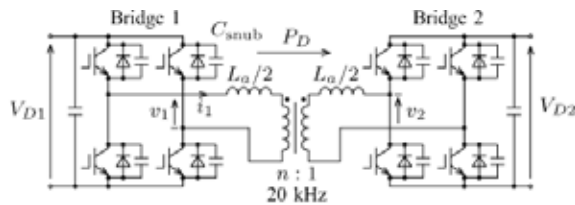


Fig.2. Bidirectional isolated dc-dc converter.

Fig.2 depicts a bidirectional isolated dc-dc converter presented in 1991. It had two symmetrical single-phase voltage-source full-bridge converters. It suffered from a low efficiency

because the first-generation IGBTs were used as switching power devices at that time. However, advancement in power device technology over the last decade has enabled the dc-dc converter to operate at an efficiency as high as 97% by using the latest trench-gate IGBTs. In addition, the use of silicon-carbide power devices in the near future will raise it to 99%. Therefore, the dc-dc converter in Fig. 2 has become a promising candidate as a power electronic interface for an energy storage system. A bidirectional converter has been discussed to exchange electric power between a fuel cell, a battery, and a load.

Fig.3 shows the energy storage system using the bidirectional isolated dc-dc converter in Fig.2. Appropriately choosing the transformer turn ratio enables to design the voltage rating of the energy storage device, independent of the utility voltage. The energy storage device is directly connected to one of the dc links of the dc-dc converter without any chopper circuit. Nevertheless, the dc-dc converter continues operating even when the voltage across the energy storage device,  $v_{D2}$  drops along with its discharge.

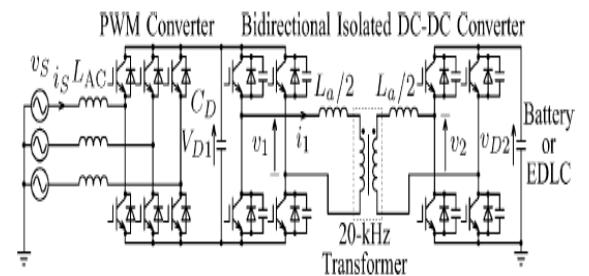


Fig. 3. Alternative energy storage system based on the bidirectional isolated dc-dc converter.

However, no paper has addressed the permissible voltage range of in terms of power loss and peak-current, and no experimental verification has been confirmed, concerning Fig.3. This paper analyzes the relationships between the power loss, the peak current, and  $v_{D2}$  in a dc-dc converter rated at 10 kW and 20 kHz with  $V_{D1}$  fixed at 320 V. Then, the dc-dc converter is designed, constructed, and tested to verify the analysis. A 2.6-kJ energy storage system using an electrolytic capacitor bank, together with the dc-dc converter, demonstrates stable charging and discharging operation. Besides, the dc-dc converter can charge the capacitor bank from zero to the rated voltage without any external pre-charging or starting-up circuit.

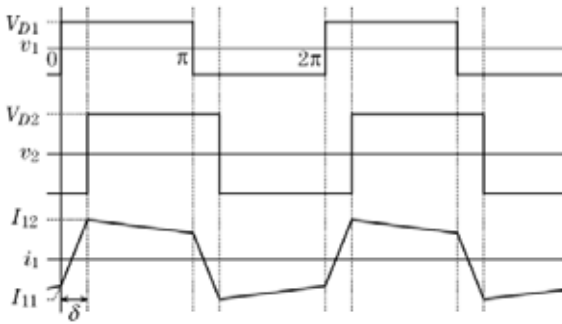


Fig. 4. Simplified theoretical waveforms used to analyze the power losses when  $V_{D1} < V_{D2}$

II. THE BIDIRECTIONAL ISOLATED DC-DC CONVERTER  
A. Operation Principle and Simplified Theoretical Waveforms

Fig.4 illustrates simplified theoretical waveforms of the dc-dc converter where  $V_{D1} < V_{D2}$ . The two single-phase voltage-source full-bridge converters produce square voltages  $v_1$  and  $v_2$ . The power transfer  $P_D$  can simply be controlled by adjusting the phase shift between  $v_1$  and  $v_2$ , is expressed by

$$P_D = \frac{V_{D1}V_{D2}}{\omega L} \left( \delta - \frac{\delta^2}{\pi} \right)$$

Where  $\omega = (2\pi f)$  is the switching angular frequency of the two single-phase voltage-source full-bridge converters, and  $L$  is the sum of the transformer leakage inductance  $L_{trans}$  and that of the auxiliary inductors  $L_a$ .

As shown in Fig. 4, this paper defines a set of two instantaneous values of the current  $i_1$  as "switching currents,"  $I_{11}$  and  $I_{12}$  which are calculated as

$$I_{11} = - \frac{(V_{D1} + V_{D2})\delta + (V_{D1} - V_{D2})(\pi - \delta)}{2\omega L}$$

and

$$I_{12} = \frac{(V_{D1} + V_{D2})\delta - (V_{D1} - V_{D2})(\pi - \delta)}{2\omega L}$$

$I_{11}$  and  $I_{12}$  are the instantaneous values of  $i_1$  when  $v_1$  and  $v_2$ , respectively, change its polarity from negative to positive.

This paper refers a single-phase voltage-source full-bridge converter as a "bridge." In the following experiments, the transformer turn ratio is unity ( $n=1$ ) for the sake of simplicity.

TABLE I

CIRCUIT PARAMETERS OF THE DC-DC CONVERTER

Rated power		10 kW
Rated DC voltage	$V_{D1}, V_{D2}$	360 V
DC capacitor	$C_D$	7,100 $\mu$ F
Unit capacitance constant	$H$	46 ms
Transformer core material		Finemet FI-3M
Transformer turn ratio	$n$	1 : 1
Transformer leakage inductance	$L_{trans}$	1.6 $\mu$ H (1.6%)
Transformer winding resistance	$R_{trans}$	17 m $\Omega$ (0.13%)
Auxiliary inductor	$L_a/2$	20 $\mu$ H (19%)
Auxiliary inductor core material		Ferrite (PC44)
Inductor winding resistance	$R_a/2$	20 m $\Omega$ (0.15%)
Snubber Capacitor	$C_{sub}$	0.01 $\mu$ F (1.6%)
Switching Frequency	$f$	20 kHz

B. Experimental Circuit of the DC-DC Converter

Table I summarizes the circuit parameters of the dc-dc converter. Four auxiliary inductors, totally having  $L_a = 40 \mu$ H, are connected in series with the transformer to obtain an inductance of  $L = 41.6 \mu$ H together with the leakage inductance of the transformer,  $L_{trans} (= 1.6 \mu$ H). The inductance of  $41.6 \mu$ H is sufficient to maintain a control resolution of power transfer around 120 W because a time resolution of the controller operated at 20 MHz is 50 ns, corresponding to  $0.36^\circ$  at 20 kHz.

The following sections analyze relationships between power transfer and power losses in the dc-dc converter. The power losses depend not only on the power transfer, but also the dc voltage  $V_{D2}$ . When  $V_{D2}$  drops along with discharge of the energy storage device, power loss increases at a given power transfer.

III. SNUBBER LOSS

A. Operating Points and ZVS Conditions

In Fig.2, a snubber capacitor  $C_{snub}$  is connected in parallel with each IGBT both to reduce switching loss and to damp out overvoltage. If the IGBT is turned on with its snubber capacitor charged, the IGBT shorts out the snubber capacitor and dissipates the energy stored in the capacitor. This paper refers to this power loss as "snubber loss."

Each IGBT can be turned on in zero-voltage switching (ZVS) manner to generate no snubber loss when both dc voltages are equal ( $V_{D1} = V_{D2}$ ), and the power transfer is sufficient to ensure the ZVS operation. However, when  $V_{D1} \neq V_{D2}$ , the IGBT is not necessarily turned on in ZVS manner.

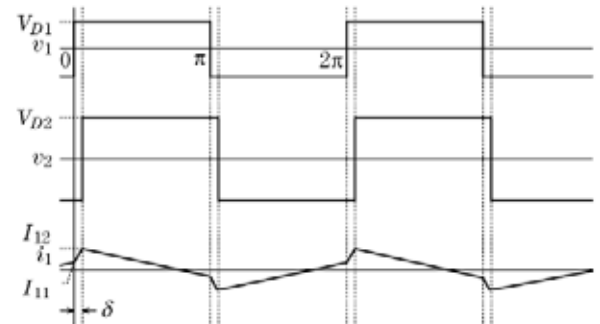


Fig. 5. Waveforms when a positive  $I$  forces bridge 1 to operate in hard-switching manner.

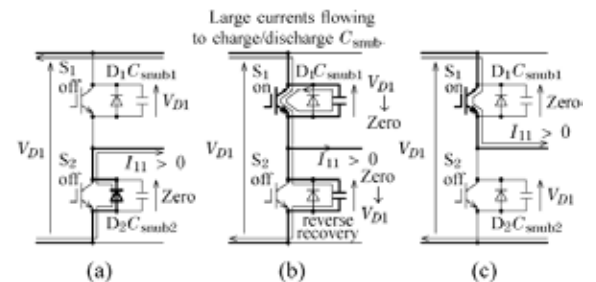


Fig. 6. Hard switching on a leg in Bridge 1: (a) just before the dead time ends, (b) rapid charging/discharging of  $C_{sub1}$ , and  $C_{sub2}$ , (c) after commutation.

Fig.5 shows simplified theoretical waveforms when the IGBTs in bridge 1 are turned on in hard-switching manner. The power transfer is less than that in Fig. 4 although the dc voltages  $V_{D1}$  and  $V_{D2}$  are the same as those in Fig.4. This so-called "reverse recovery" occurs in the free-wheeling diodes in bridge 1 because the switching current  $I_{11}$  is positive as can be seen in Fig. 5. However, the four IGBTs in bridge 2 are returned on in ZVS manner. One can classify the turn-on processes of the

IGBTs in bridges 1 and 2 into the following three: 1) hard switching operation; 2) incomplete ZVS operation; and 3) ZVS operation, depending on the power transfer  $P_D$ , the phase shift  $\delta$ , the dc voltages  $V_{D1}$  and  $V_{D2}$ , and the deadtime. The hard-switching operation and the incomplete ZVS operation can take place only in one bridge, whose dc voltage is lower than the other. The following calculations mainly focus on phenomena in bridge 1 because those in bridge 2 can be described alike.

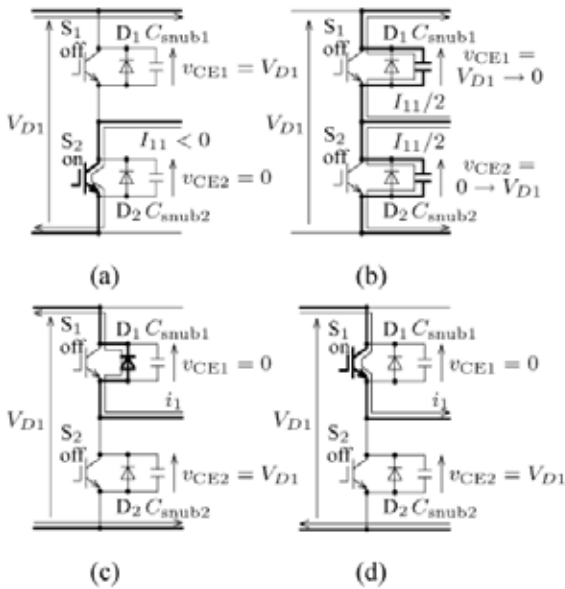
**B. Calculations of the Snubber Loss**

**1) Hard-Switching Operation:** Fig.6 shows circuit modes when a leg (for example, consisting of  $S_1$  and  $S_2$ ) operates in hard-switching manner. The IGBTs in bridge 1 are turned on in hard-switching manner if the dc voltage  $V_{D1}$  is lower than  $V_{D2}$ , and the following equation is satisfied:

$$\delta \leq \frac{V_{D2} - V_{D1}}{2V_{D2}} \pi$$

The snubber capacitor of  $S_1$  or  $C_{snub1}$  has been charged at [see Fig. 6(a)] before the end of the dead time. Just after  $S_1$  is turned on,  $D_2$  experiences reverse recovery.  $C_{snub1}$  discharges from  $V_{D1}$  to zero while  $C_{snub2}$  charges from zero to  $V_{D1}$  [see Fig. 6(b)]. Only an equivalent resistance of  $S_1$  limits the charging/discharging currents, resulting in a joule loss of  $W_{snub} = C_{snub} V_{D1}^2$ . Note that  $W_{snub}$  represents an amount of energy lost at one switching per leg where  $C_{snub1} = C_{snub2} = C_{snub}$ . Then, the snubber loss  $P_{snub1}$  in bridge 1 is calculated as

$$P_{snub1} = 4W_{snub1}f = 4C_{snub}V_{D1}^2f$$



**Fig. 7. ZVS on a leg in Bridge 1: (a) just before the dead time starts, (b) just after the dead time starts, (c) diode free wheeling, and (d) current polarity alternates after the dead time.**

**2) ZVS Operation:** Fig.7 shows circuit modes when a leg in bridge 1 operates in ZVS manner. Before the dead time, the current of  $I_{11}$  is flowing in  $S_2$  [see Fig. 7(a)]. Turning off  $S_2$  starts the dead time. The current flowing in  $S_2$  is commutated to  $C_{snub1}$  and  $C_{snub2}$ . A resonance begins between the inductance  $L$  (see Fig. 2),  $C_{snub1}$  and  $C_{snub2}$ .  $C_{snub1}$  discharges from  $V_{D1}$  to zero while  $C_{snub2}$  charges from zero to  $V_{D1}$ . Once  $C_{snub1}$  discharges down to zero, the current is commutated to  $D_1$  [see Fig. 7(c)]. Providing a gating signal during conduction of  $D_1$  makes  $S_1$  ready to conduct the current.  $S_1$  actually starts to

conduct the current in ZVS manner after the current in  $D_1$  decays to zero and alternates its polarity [see Fig. 7(d)]. This operation results in no snubber loss.

**3) Incomplete ZVS Operation:** The IGBTs in bridge 1 can not necessarily be turned on in ZVS manner even if the switching current  $I_{11}$  is negative. Unlike in the ZVS operation,  $C_{snub1}$  does not discharge down to zero, and  $C_{snub2}$  does not charge up to  $V_{D1}$ , if the magnitude of  $I_{11}$ , or  $|I_{11}|$  is smaller than  $I_{min}$ , where

$$I_{min} = \frac{2\sqrt{V_{D1}V_{D2}}}{Z_r}$$

and

$$Z_r = \sqrt{\frac{L}{C_{snub}}}$$

In this case, the operation of the leg makes a direct transition from Fig.7(b) to (d), not through (c). Turning on  $S_1$  with the charged snubber capacitor  $C_{snub1}$  results in an amount of snubber loss. This paper refers to this as "incomplete ZVS operation."

The following is the calculation of the snubber loss caused by the incomplete ZVS operation. The collector-emitter voltage of  $S_1$ ,  $v_{CE1}$  in Fig. 7(b) can be expressed as

$$v_{CE1}(t) = \frac{(V_{D1} + V_{D2}) + (V_{D1} - V_{D2}) \cos \omega_r t}{2} - \frac{Z_r |I_{11}| \sin \omega_r t}{2}$$

where  $t$  is the time after the dead time starts, and  $\omega_r (= 1/\sqrt{LC_{snub}})$  is the resonant angular frequency of  $C_{snub}$  and  $L$ . The collector-emitter voltage  $v_{CE1}(t)$  is not zero at the end of the dead time. As a result, the IGBT dissipates an energy of  $W_{snub1} = C_{snub} v_{CE1}^2$  when it is turned on. Therefore, the snubber loss  $P_{snub1}$  in bridge 1 is calculated as

$$P_{snub1} = 4f C_{snub} \{v_{CE1}(T_d)\}^2$$

As can be seen in (5) and (9), the snubber loss is proportional to the capacitance of the snubber capacitors. Minimizing the parasitic inductance leads to the use of small snubber capacitors without an excessive overvoltage appearing across an IGBT, thus resulting in reducing the snubber loss.

**IV. PROFILE OF THE CURRENT AND RELATED LOSSES**

**A. Conducting Loss in the IGBTs**

This paper approximates both the on-state voltage across the IGBT,  $V_{CE(sat)}$ , and the forward voltage drop across the freewheeling diode,  $V_f$ , to be 1.5V, that is,  $V_{CE(sat)} = V_f = 1.5V$ , independent of the current flowing in them. The conducting loss in the IGBTs and diodes,  $P_{cond}$  can be calculated from the average of the absolute value of the current  $i_1$ . When either bridge 1 or bridge 2 is operated in hard-switching manner, calculation on Fig. 5 yields:

$$\langle |i_1| \rangle = \frac{1}{\omega L} \left\{ \frac{V_{D1}V_{D2}}{|V_{D1} - V_{D2}|} \frac{\delta^2}{\pi} + |V_{D1} - V_{D2}| \frac{\pi}{4} \right\}$$

On the other hand, when both bridge 1 and bridge 2 are operated in either ZVS or incomplete ZVS manner,  $\langle |i_1| \rangle$  can be calculated from Fig. 4:

$$\langle |i_1| \rangle = \frac{V_{D1}V_{D2}}{\omega L(V_{D1} + V_{D2})} \left\{ -\frac{\delta^2}{\pi} + 2\delta + \frac{(V_{D1} - V_{D2})^2 \pi}{4V_{D1}V_{D2}} \right\}$$

Both  $I_{11}$  and  $I_{12}$  have to be obtained first to calculate  $\langle |i_1| \rangle$ , and then either (10) or (11) should be applied, depending on the switching manner.

**B. Copper Loss in the Transformer and the Auxiliary Inductors**

Calculation on the waveforms in Figs. 4 and 5 yields the rms value of  $i_1$ , or  $i_2$ .

$$I_1 = \frac{\sqrt{V_{D1}V_{D2}}}{\omega L} \sqrt{-\frac{4}{3\pi}\delta^3 + \delta^2 + \frac{\pi^2}{12} \frac{(V_{D1} - V_{D2})^2}{V_{D1}V_{D2}}}$$

regardless of the switching manner. The copper loss in the transformer and the inductors,  $P_{copp}$ , is obtained as

$$P_{copp} = (R_{trans} + R_a) \cdot I_1^2$$

where  $R_{trans}$  ( $=17m\Omega$ ) is the winding resistance of the transformer, and  $R_a$  ( $=40m\Omega$ ) is that of the auxiliary inductors.

**C. Core Loss in the Auxiliary Inductors**

The four auxiliary inductors were constructed using ferrite (TDK PC44) cores. The effective cross-sectional area of each core was  $A_e = 328 \text{ mm}^2$ , the effective volume was  $V_e = 37.2 \text{ cm}^3$ , and the turn number was  $N$ . An air gap of  $\delta$  was introduced in the magnetic path. Thus, the instantaneous magnetic flux density is approximately expressed as

$$b_{ind} = \mu_0/g N i_1$$

where  $\mu_0$  is the permeability of vacuum. The datasheet of PC44 indicates that its core loss per volume is  $600 \text{ kW/m}^3$  when the maximum flux density is  $200 \text{ mT}$  at a frequency of  $100 \text{ kHz}$  at a temperature of  $25^\circ\text{C}$ .

In a power electronic context, the Steinmetz equation helps well to calculate an amount of core loss in a magnetic material where  $k$  is a material constant,  $f$  is a frequency of magnetization, and  $B$  is the maximum flux density. The exponents,  $\alpha$  and  $\beta$ , are not constant values, but depend on  $f$ ,  $B$ , and the waveform of the magnetic flux. When a ferrite core is excited at  $20 \text{ kHz}$ , the eddy-current loss can be much smaller than the hysteresis loss. Thus,  $\alpha$  is assumed to be unity. The other exponent  $\beta$  usually ranges from  $2.6$  to  $2.8$ . However, this paper takes an approximation of  $\beta=2$  so as to keep the analysis simple. This approximation allows to treat the core loss in the same way as the copper loss.

If the core loss per volume in PC44 can be approximated by  $m f B^2$ , the coefficient  $m$  is given as  $0.15 \text{ mW/HzT}^2$ . This paper assumes that a sinusoidal  $20\text{-kHz}$  current having an rms value as large as  $I_1$  is responsible for the core loss in the auxiliary inductors. The core loss in the four auxiliary inductors can be calculated as

$$P_{core}[\text{W}] = 4m f \left( \frac{\mu_0 N \sqrt{2} I_1}{g} \right)^2 V_e = \frac{8m f \mu_0^2 N^2 V_e}{g^2} I_1^2$$

where  $\sqrt{2}$  is the coefficient to transform an rms value into an amplitude. Therefore, the core loss in the four auxiliary inductors can be treated as an equivalent winding resistance of

$$R_{core(ind)} = \frac{8m f \mu_0^2 N^2 V_e}{g^2} = 23 \text{ m}\Omega$$

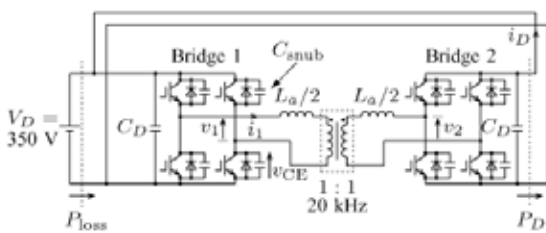


Fig 8. Experimental circuit to measure the power loss of the dc-dc converter.

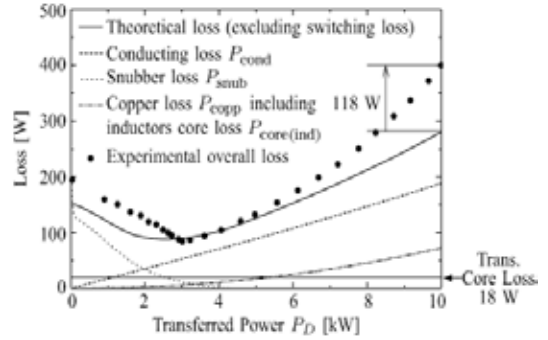


Fig 9. Comparison between calculated and experimental power losses at  $V_{D1} = V_{D2} = 350 \text{ V}$ .

This equivalent resistance enables to calculate the core loss in the auxiliary inductors as a part of copper loss. Further detailed analysis, should bring an improvement of accuracy to the core-loss calculation although it is out of the scope of this paper.

**V. POWER LOSSES AND LOWER LIMIT OF  $V_{D2}$**   
**A. Comparison Between Theoretical and Experimental Losses**

Theoretical losses described in the previous section are compared to measured results on the basis of an experimental dc-dc converter rated at  $10 \text{ kW}$  and  $20 \text{ kHz}$ . Fig.8 shows the experimental circuit to measure the overall loss of the dc-dc converter. The circuit parameters in Fig.8 are the same as those in Table I. Both theoretical calculation and experimental measurement are carried out under  $V_{D1} = V_{D2} = 350 \text{ V}$ .

Note that in Fig.8 is a dc voltage source. A connection between the two dc links allows the power  $P_D$  to be regenerated back to the dc voltage source. Thus, the power coming from  $V_D$  equals  $P_{loss}$ , that is the overall loss in the dc-dc converter.

Fig. 9 shows comparisons between the theoretical and experimental losses. The solid line corresponds to the theoretical overall loss  $P_{theory}$ , although it excludes the switching loss in the IGBTs. Even in the ZVS operation, the switching loss is not zero due to the so-called "tail current" in the IGBTs. It requires modeling of the IGBT switching behavior in this dc-dc converter to theoretically predict the switching loss  $P_{sw}$ . However, it is beyond the scope of this paper.

When  $P_D = 10 \text{ kW}$ , the theoretical losses were obtained as follows. The conducting loss was  $P_{cond} = 189 \text{ W}$ . The snubber loss was  $P_{snub} = 0 \text{ W}$ . The copper loss both in the transformer and the inductors  $P_{copp} = 73 \text{ W}$  including the core loss in the inductors,  $P_{core(ind)}$ . The core loss in the transformer was,  $P_{core(tr)} = 18 \text{ W}$ , almost independent of the power transfer. Thus, the theoretical overall loss is  $282 \text{ W}$ .

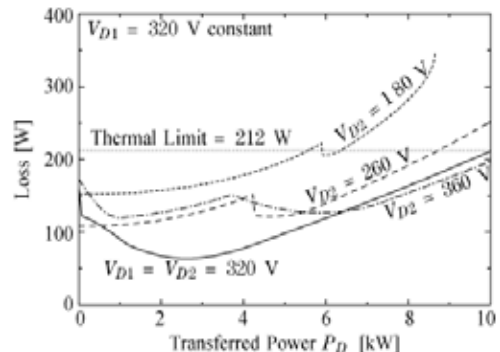


Fig 10. Sum of theoretical conducting and snubber losses ( $P + P$ ) when  $P$  is positive.

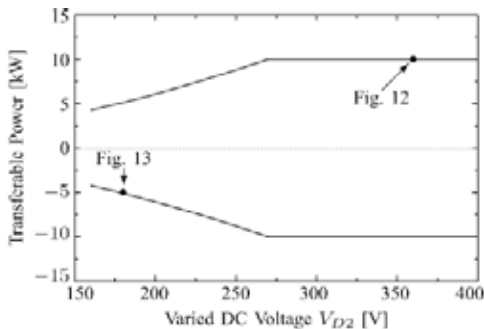
The experimental results,  $P_{loss}$ , on the other hand, was 400 W. Thus, the difference between the theoretical and measured results were 118 W. It would include the switching loss in the IGBTs that was excluded from the theoretical overall loss. Although the difference of  $118W - 90W = 28W$  can't be identified, the theoretical calculations can be valid because the error of 28W corresponds to 0.28% of the power transfer of 10 kW, and 7% of the measured overall loss of 400 W.

A 250-V, 5-kW bidirectional isolated dc-dc converter was constructed and tested in . The dc-dc converter employed the third-generation planar-gate IGBTs rated at 600 V and 100 A. The overall loss of the dc-dc converter was measured at six switching frequencies from 10 to 20 kHz with a step of 2 kHz. This measurement enabled to extract the switching loss from the overall loss because the switching loss is proportional to the switching frequency. As a result, the switching loss was approximately 75 W at a power transfer of 5 kW and a switching frequency of 20 kHz. The switching loss of 90 W in the 350-V, 10-kW dc-dc converter in this paper can be a reasonable value, considering the raised voltage from 250 V to 350 V, the increased power from 5 to 10 kW, and the use of the latest trench-gate IGBTs.

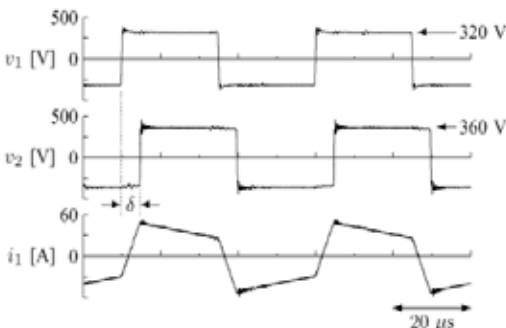
**B. Thermal Limit and  $V_{D2}$**

Fig. 10 shows calculated results of conducting and snubber losses in the IGBTs when the power transfer is positive. Once dc voltage was kept constant at 320V, while the other dc voltage was changed as a parameter. Achieving the ZVS operation becomes difficult with  $V_{D1} \neq V_{D2}$ , compared to  $V_{D1} = V_{D2} = 320V$ , resulting in an increased snubber loss around  $P_D = 3kW$ .

Fig. 10 defines  $P_{cond} + P_{snub} = 212W$  at  $V_{D1} = V_{D2}$  as a "thermal limit." The losses in the IGBTs, which are the most dominant in the overall loss, may make the IGBT modules mounted on a heatsink suffer from the highest temperature. The temperature of the IGBT modules, more precisely these semiconductor chips in the modules, determines the maximum power transfer. Therefore, this paper considers only the losses in the IGBT modules as the thermal limit.



**Fig. 11. Transferable powers when the peak value of current  $i_1$  is limited to 60A, and two operating points in experiments.**



**Fig. 12. Experimental waveforms when  $V_{D1} = 320V$ ,  $V_{D2} = 360V$ ,  $\delta = 35^\circ$ , and  $P_D = 10kW$ .**

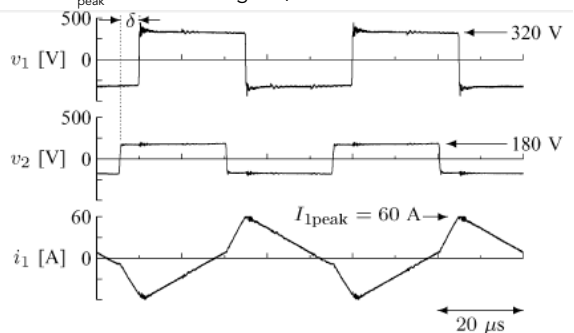
When  $V_{D2} = 180V$ , the losses in the IGBTs exceed the thermal limit at  $P_D > 5.6kW$ . Hence, when  $V_{D2} = 180V$ , the dc-dc converter has to operate under 5.6 kW. When  $V_{D2} = 260V$ , the losses in the IGBTs exceed the thermal limit at  $P_D > 8.6kW$ . Likewise, the dc voltage imposes limitations on maximum power transfer.

**VI. PEAK CURRENT IN THE AUXILIARY INDUCTORS**

The ferrite cores in the auxiliary inductors would be magnetically saturated if the current  $i_1$  exceeds 60 A because the magnetic flux density reaches 0.3 T as calculated by (14). The dc-dc converter has to be operated considering the limitation on the peak value of  $i_1$ . The peak current imposes limitation on the dc voltage  $V_{D2}$ . When  $V_{D1} > V_{D2}$ , the peak current  $I_{1peak}$  equals  $I_{11}$ . When  $V_{D1} < V_{D2}$ , the peak current  $I_{1peak}$  equals  $I_{12}$ .

Fig.11 shows maximum power transfer when the peak current is limited lower than 60 A. Solid dots "•" indicate the operating points of the waveforms shown in Figs. 12 and 13. When  $V_{D2} = 180V$ ,  $I_{1peak}$  exceeds 60 A at  $P_D = 5.1kW$ . When  $V_{D2} = 260V$ ,  $I_{1peak}$  exceeds 60 A at  $P_D = 9.4kW$ . Both the power loss and the peak current impose limitations on the power transfer  $P_D$  and the dc voltage  $V_{D2}$ . Operation of the dc-dc converter has to satisfy both limitations.

Fig. 12 shows the observed waveforms when one dc voltage is 320V while the other is 360V at  $P_D = 10kW$  from bridges 1 to 2. Fig. 13 shows another example of the observed waveforms which was taken when  $V_{D1} = 320V$  while  $V_{D2} = 180V$  at  $P_D = 5kW$  from bridges 2 to 1. The power transfer  $P_D$  was limited below 5 kW, as shown in Fig. 11 when the dc-dc converter had a set of dc voltages of  $V_{D1} = 320V$  and  $V_{D2} = 180V$ . The peak current  $I_{1peak}$  was 60 A in Fig. 13, as calculated in this section.



**Fig. 13 Experimental waveforms when  $V_{D1} = 320V$ ,  $V_{D2} = 180V$ ,  $\delta = -41^\circ$ , and  $P_D = -5kW$ .**

**VII. APPLICATION TO AN ENERGY STORAGE SYSTEM**

**A. The 200-V, 10-kW, 2.6-kJ Laboratory Model:**

Fig.14 depicts the experimental energy storage system rated at 200 V, 10 kW, and 2.6 kJ. Circuit parameters in the dc-dc converter were the same as those in Table I. An electrolytic capacitor bank of 60,000µF was used to simulate an EDLC bank. The capacitor bank is charged up to 350 V and discharged down to 190 V. Thus, an energy of 2.6 kJ is stored into, and released out of, the capacitor bank. It corresponds to 70% of the energy stored in  $C_{ES}$  at  $v_{D2} = 350V$ . The carrier frequency of the PWM converter used as the front end was 10 kHz.

**B. Charging and Discharging of the Capacitor Bank**

Fig.15 shows the observed waveforms when the energy storage capacitor bank  $C_{ES}$  was repetitively charged up to 350 V, and then discharged down to 190 V. The waveform of  $v_{D2}$  was observed via a low-pass filter with a cut-off frequency of 800 Hz. The maximal power transfer was 9.3 kW. In this experiment, the phase shift had a square waveform with an amplitude of 30° to make the controller simple. In actual energy storage systems, however, the power transfer  $P_D$  should be given by power demand, or a higher level controller regulating the voltage on the utility grid.

VIII. STARTING PROCEDURE

At the starting of the system, an inrush current would flow into the auxiliary inductors  $L_a$  and the transformer if bridge 1 produced a square voltage of  $v_1$ ,  $v_{D1} = 320$  V and  $v_{D2} = 0$  V. The inrush current would result in magnetic saturation in the cores of  $L_a$ , leading to an even larger inrush current. Hence, this paper presents a special operation mode called "pre-charging operation" to charge the capacitor bank from zero to the rated voltage of 320 V, preventing such an inrush current from flowing. The pre-charging operation allows the energy storage system to require no external starting-up or pre-charging circuit. The pre-charging operation presented in this paper can be considered as a well-known "soft-start" procedure of dc-dc converters. However, experimental verification of the pre-charging operation makes a technical contribution to the energy storage system with the large dc capacitor bank.

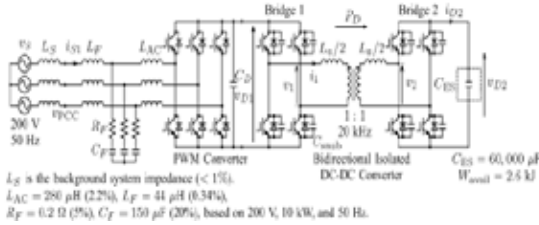


Fig.14. A 200 V, 10kW experimental circuit with energy-storage electrolytic capacitors of 60 000μF to simulate an EDLC bank.

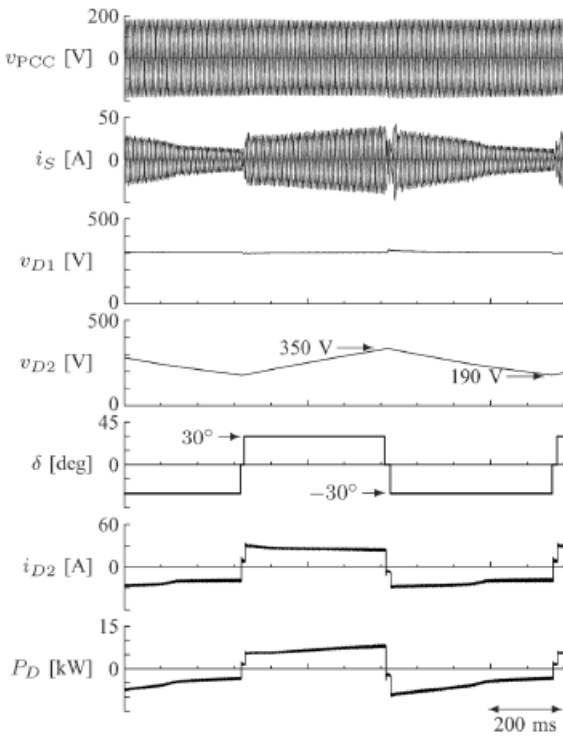


Fig.15. Experimental waveforms of charging and discharging of the capacitor bank ( $W_{avail} = 2.6$  kJ).

Fig.16 shows the starting-up and pre-charging transient waveforms of the dc-dc converter when the capacitor bank began being charged from 0 to 320 V. In this experiment,  $v_{D2}$  had been already charged up to 320 V before the dc-dc converter started the pre-charging operation. Bridge 1 produced a voltage  $v_1$  with a duty ratio of rather than 100% while bridge 2 was operated as a diode rectifier with all the IGBTs kept off. The first pulse of  $v_1$  had a half duty ratio of  $d/2 = 10\%$  to

suppress dc magnetization of the transformer. The peak value of the first pulse of  $v_1$ ,  $I_{1pp}$  is expressed as

$$I_{1pp} = \frac{\pi V_{D1} d}{\omega L \frac{d}{2}}$$

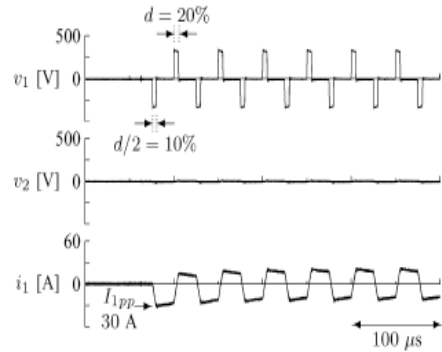


Fig.16. Transient waveforms when the dc-dc converter starts pre-charging the capacitor bank.

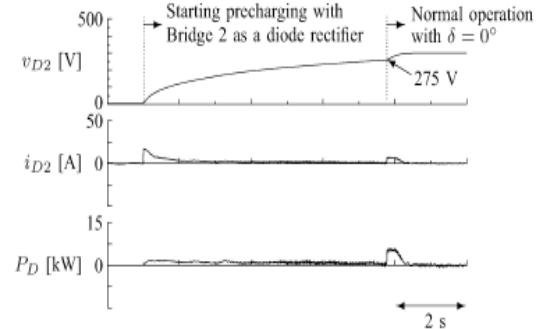


Fig.17. Experimental waveforms of dc voltage, current, and power in the pre-charging period.

The negative peak current reached 30 A in Fig. 16 while its theoretical value was 19.2 A. Fig. 17 shows the experimental waveforms of the dc voltage, current, and power. The starting procedure took approximately 8 s to charge the capacitor bank from zero to 320 V. No excessive inrush current flowed into the capacitor bank. When the voltage across the capacitor bank,  $v_{D2}$  reached 275 V, the dc-dc converter changed its operation mode from the pre-charging operation to the normal operation with the square voltages of  $v_1$  and  $v_2$  having no phase shift ( $d = 100\%$  and  $\delta = 0^\circ$ ). The power transfer  $P_D$  in the normal operation at  $\delta = 0^\circ$  has a negative-feedback effect to balance the two dc voltages  $v_{D1}$  and  $v_{D2}$  due to the existence of the dead time. Therefore,  $v_{D2}$  was charged up to the same voltage as  $v_{D1}$  naturally after  $v_{D2}$  reached 275 V.

IX. CONCLUSION

This paper has addressed a bidirectional isolated dc-dc converter suitable for an energy storage system. Theoretical calculations of power losses and peak current have clarified the dc-voltage limitations in the energy storage system. Experimental results have revealed that the dc-dc converter can charge and discharge the capacitor bank properly. Moreover, the dc-dc converter can charge the capacitor bank from zero to the rated voltage without any external pre-charging circuit.

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