



ON THE RELATIONSHIP BETWEEN AN ORTHOGONAL AND A COMPLETE REDUCIBLE CONTINUOUS LINEAR REPRESENTATION

KEYWORDS

Topological group, bilinear function, orthogonal and completely reducible continuous linear representation

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ABSTRACT

A continuous linear representation ρ_c is a homomorphism from a topological group G into $GL_c(V)$ of all continuous bijective transformations. Representation c is called an orthogonal if on the topological vector space V there is a positive definite symmetric bilinear function f invariant under c . Furthermore, c is said to be completely reducible if every invariant subspace U of V has an invariant complement W . We have every orthogonal representation is completely reducible. Especially for a continuous linear representation from a compact topological group.

1 Introduction

A topological vector space is a vector space that is completed by a topology and satisfies some axioms of continuous function properties [7]. A topological group is a group that is a topological space satisfying two axioms of continuity function [2]. The relationship among groups and vector spaces is given by a map which is called a linear representation. A linear representation of a finite group has been discussed by some researchers, such as Verlag and Pierre [8,9]. Many applications of linear representation of a finite group have been done. In 2009, Palupi et al [4a] discussed the construction of topology on $L_c(V)$ and in the same year, they defined a continuous linear representation from a topological group into a topological vector space [4b]. And then Palupi do more research on the continuous linear representation until now. The topological vector space V is said to be the representation space. So, the continuous linear representation to represent an abstract space into a real space, as a complex number set or a real number set.

Furthermore, a topological vector subspace $U \subseteq V$ is said to be an invariant under a continuous linear representation c , if there is a topological vector subspace W which is an invariant under ρ_c too, such that $U \oplus W = V$.

In the otherside, we can choose a real representation space is Euclidean space or Hilbert space. The continuous linear representation ρ_c is called an orthogonal if we can define a bilinear function on the Euclidean or Hilbert space.

1.1 Continuous Linear Representation

Let $L_c(V)$ be a topological vector space, where $L_c(V)$ is a collection of all continuous linear operator from V into himself. Let $GL_c(V) = \{T: V \rightarrow V \text{ linear, continuous and bijective}\}$. The set $GL_c(V)$ is not empty and $GL_c(V) \subset L_c(V)$. Furthermore, by a topology GL , that is an induced by topology L on $L_c(V)$ and restriction continuous maps f_L and g_L of $L_c(V)$ on $GL_c(V)$, we have $GL_c(V)$ is a topological vector subspace of $L_c(V)$. Under a composition operation, $GL_c(V)$ is a topological group.

Now, let (G, μ) be a topological group. Since G is a group then for every $x, y \in G$, $xy \in G$. We can define a map P_c from (G, μ) into $GL_c(V)$ such that for every $x, y \in G$, $P_c(xy) = P_c(x) P_c(y)$. Notice that for the identity element $e \in G$, $P_c(x) = P_c(ex) = P_c(xe) = P_c(x) P_c(e) = P_c(x) P_c(e)$. Thus, $P_c(e)$ is the identity element in $GL_c(V)$. Since for each $x \in G$ there is an inverse element $x^{-1} \in G$ such that $xx^{-1} = x^{-1}x = e$, $P_c(xx^{-1}) = P_c(x) P_c(x^{-1}) = P_c(e) = P_c(x^{-1}x) = P_c(x^{-1}) P_c(x)$, then $P_c(x^{-1}) = (P_c(x))^{-1}$. By considering the definition of $GL_c(V)$, for every $x \in G$, there exists an element in $GL_c(V)$ as the image of P_c at x .

We write the image of P_c at x by $T_{c,x}$ for every $x \in G$. That means, $P_c(x)$ will be written by $T_{c,x}$, for every $x \in G$. For next discussion, P_c denotes a

map from (G, μ) into $(GL_c(V), \tau_{GL_c})$ such that $P_c(xy) = P_c(x) P_c(y)$, for every $x, y \in G$. The map P_c has characteristic as stated in Theorem 1.1.1

Theorem 1.1.1 Let (G, μ) and $(GL_c(V), \tau_{GL_c})$ be topological groups. A map $\rho_c: (G, \mu) \rightarrow (GL_c(V), \tau_{GL_c})$ is a continuous homomorphism.

Furthermore, if we have a map P_c in Theorem 2.1, we define a representation concept as follow.

Definition 1.1.2 Let (G, μ) be a topological group and (V, σ) be a topological vector space. In Theorem 1.1.1, a map c from (G, μ) into $(GL_c(V), \tau_{GL_c})$ satisfies:

- $\rho_c(y) = \rho_c(x) \circ \rho_c(y)$
- $\rho_c(x^{-1}) = (P_c(x))^{-1}$, for every $x, y \in G$.
- ρ_c is continuous

A map ρ_c state like above, is called a continuous linear representation.

The existence of this representation is a homomorphism ρ_c from an arbitrary topological group into an arbitrary topological vector space which is defined as $\rho_c(x) = \rho_c(e)$ for every $x \in G$ where $\rho_c(e)$ is identity element $I_{c,x}$ in $GL_c(V)$.

Let (V, σ) be a topological vector space, by considering an induced topology, every subspace U of V is a topological vector subspace such that we can write as (U, σ_U) where σ_U is a topology induced by σ . A topological vector subspace U of V is called invariant over ρ_c if $\rho_c(x)(u) = T_x(u)$ in U , for every $x \in G$ and $u \in U$. Irreducibility and reducibility of continuous linear representation are listed in the following definition.

Definition 1.1.3 A continuous linear representation c from a topological group (G, μ) into a topological vector space (V, σ) is called irreducible if invariant topological vector subspaces of V over c are only $\{0\}$ and (V, σ) . A continuous linear representation c is called complete reducible if every invariant topological vector subspace U of V over c , there is an invariant topological vector subspace W of V over ρ_c such that $U \oplus W = V$.

1.2 Bilinear function.

On this sub bab 1.2, we have declared the bilinear function which is symmetric, positive definite and invariant under a representation. Let V_n be the real vector space or V_c be the complex vector space.

Definition 1.2.1 Let V be an inner product space. The Function h from $V \times V$ into a field F (complex or real) is called sesquilinear if it satisfies

- $h(x_1 + x_2, y) = h(x_1, y) + h(x_2, y)$
- $h(x, y_1 + y_2) = h(x, y_1) + h(x, y_2)$
- $h(\alpha x, y) = \alpha h(x, y)$,

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