

On Semi- Slant Submanifolds of a Nearly Sasakian Manifold



Mathematics

KEYWORDS : Contact manifolds, Semi slant submanifolds, Nearly sasakian manifolds, Integrable distribution

Shyam Kishor

Assistant Professor, Universty of Lucknow, Lucknow-226007, India

ABSTRACT

The object of the present chapter is to study the semi- slant submanifolds of a nearly Sasakian manifold. The conditions for some distributions on the semi- slant submanifolds of a nearly Sasakian manifold to be autoparallel has been explored. Further, the integrability conditions for some distributions has also been discussed.

1. Introduction

Slant immersions in complex geometry were dened by Chen as a natural generalization of both holomorphic immersions and totally real immersions [1]. Lotta has introduced the notion of slant immersion of a Riemannian manifold into an almost contact metric manifold [2]. Papaghiuc has introduced a class of submanifolds in an almost Hermitian manifold, called the semi-slant submanifolds [3], such that the class of proper CR- subman-ifolds and the class of slant submanifolds appear as particular cases in the class of semi-slant submanifolds. The concept of the differential geometry of semi- invariant or contact CR submanifolds, as a generalization of invariant and anti-invariant submanifolds, of an almost contact metric manifold was given by Bejancu [9] and extended by many other ge-ometers([8],[7]). In 1999, Cabrerizo et.al.[4] have worked on the "Semi- Slant Submanifolds of a Sasakian Manifold ". From this, we have motivated and study semi slant submanifolds of a nearly Sasakian manifold.

2. Preliminaries

A $(2n + 1) -$ dimensional Riemannian manifold (M, g) is said to be an almost contact manifold if there exist on M a $(1,1)$

*Department of Mathematics & Astronomy, University of Lucknow, Lucknow-226007, India.

E-mail: skishormath@gmail.com

tensor field ϕ , a unique global non vanishing vector field ξ (called the structural vector field), a 1-form η and a compatible Riemannian metric g s.t.

$$(2.1) \quad \phi^2 = -I + \eta \otimes \xi,$$

$$\eta(\xi) = 1, \quad \phi\xi = 0 \quad \eta \circ \phi = 0$$

$$(2.2) \quad g(\phi X, \phi Y) = g(X, Y)$$

$$- \eta(X)\eta(Y)$$

$$(2.3) \quad g(\phi X, Y) = -g(X, \phi Y), \\ g(X, \xi) = \eta(X),$$

for all vector fields X, Y on M .

An almost contact metric manifold M with almost contact metric structure (ϕ, ξ, η, g) is called a nearly Sasakian manifold if

$$(2.4) \quad (\tilde{\nabla}_X \phi)Y + (\tilde{\nabla}_Y \phi)X \\ = 2g(X, Y)\xi - \eta(Y)X \\ - \eta(X)Y$$

Let M be a submanifold of a Riemannian manifold M with a Riemannian metric g then the Gauss and Weingarten formulae are given by

$$(2.5) \quad \tilde{\nabla}_X Y = \nabla_X Y + \sigma(X, Y)$$

$$(2.6) \quad \tilde{\nabla}_X V = -A_V X + \nabla^\perp X,$$

for any $X, Y \in TM, V \in V^\perp M$; where $\tilde{\nabla}, \nabla$ and ∇^\perp are respectively the Riemannian, induced Levi- Civita and normal connections in M, M and the normal bundle $T^\perp M$ of M respectively then

σ is the second fundamental form related to Weingarten map associated with V denoted by A_V , defined as

$$(2.7) \quad g(\sigma(X, Y), V) = g(A_V X, Y)$$

For any $x \in M$, $X \in TM$ and $V \in T^\perp M$, we have

$$(2.8) \quad (\tilde{\nabla}_X \phi)Y = \{(\nabla_X H)Y - A_{LY}X - h\sigma(X, Y)\} + \{(\nabla_X L)Y + \sigma(X, HY) - l\sigma(X, Y)\}$$

$$(2.9) \quad (\tilde{\nabla}_X \phi)V = \{(\nabla_X h)V - A_{LV}X - HA_V X\} + \{(\nabla_X l)V + \sigma(X, hV) - LA_V X\},$$

where ϕ is a (1,1) tensor field on M

and

$$(2.10) \quad \phi X = HX + LX;$$

$$HX \in T_x M, \quad LX \in T_x^\perp M$$

$$(2.11) \quad \phi V = hV + lV;$$

$$hV \in T_x M, \quad lV \in T_x^\perp M$$

$$(2.12) \quad (\nabla_X H)Y = \nabla_X H Y - H \nabla_X Y; \quad (\nabla_X L)Y = \nabla_X^\perp L Y - L \nabla_X Y;$$

$$(2.13) \quad (\nabla_X h)V = \nabla_X h V - h \nabla_X^\perp V;$$

$$(\nabla_X l)V = \nabla_X^\perp l V - l \nabla_X^\perp V;$$

for any $X, Y \in TM$ and $V \in T^\perp M$.

From equation (2.3) and (2.10), we have

$$(2.14) \quad g(HX, Y) = -g(X, HY)$$

for each $x \in M$, and $X, Y \in T_x M$.

3. Semi- Slant Submanifolds of Nearly Sasakian Manifolds

A submanifold M of an almost contact metric manifold M is said to be slant submanifold if for any $x \in M$ and $X \in T_x M$, linearly independent on ξ , the angle between ϕX and $T_x M$ is constant. The constant angle $\theta \in [0, \pi/2]$ is then called the slant angle or Wirtinger angle of M in M . If $\theta = 0$, the submanifold is invariant submanifold and if $\theta = \pi/2$, then submanifold is anti- invariant submanifold. If $\theta \neq 0, \pi/2$ then the submanifold is called a proper slant submanifold.

Definition 3.1 : A submanifold M is said to be a semi- slant submanifold of M if there exist two orthogonal distributions D_1 and D_2 on M such that at each point $x \in M$, the following conditions

(i) $T_x M$ admits an orthogonal direct decomposition i.e. $T_x M = D^1 \oplus D^2 \oplus \{\xi\}$

(ii) The distribution D_1 is an invariant distribution, i.e. $\phi(D_1) = D_1$

(iii) The distribution D_2 is slant with angle $\theta \neq 0$ hold;

where $\{\xi\}$ denotes the distribution spanned by the structure vector field ξ .

*Department of Mathematics & Astronomy, University of Lucknow, Lucknow-226007, India.

E-mail: skishormath@gmail.com

It is obvious that invariant distribution of a semi- slant submanifold is a slant distribution with zero angle. Then it is obvious that semi- slant submanifolds are particular case of bi-slant submanifolds. Similarly we say M is anti- slant submanifold of M ; if D_1 is an anti-invariant distribution of M i.e. $\phi(D_1) \subseteq T^\perp M$ and D_2 is slant with slant angle $\theta \neq 0$. Moreover, if $\theta = \pi/2$, then semi- slant submanifold is a semi- invariant submanifold.

For a semi- slant submanifold M , denote P_i the projection on the distribution D_i ; $i = 1, 2$

$$(3.1) \quad X = P_1X + P_2X + \eta(X)\xi,$$

for any $X \in TM$,

where P_iX denotes the component of $X \in D_i$; $i = 1, 2$.

Applying ϕ on (3.1), we have

$$(3.2) \quad \phi X = \phi P_1X + HP_2X + LP_2X.$$

It is easy to see that, for any $X \in TM$

$$(3.3) \quad \phi P^1X = HP^1X$$

$$\text{and } LP_1X = 0,$$

$$(3.4) \quad HP_2X \in D_2$$

In particular, we obtain

$$(3.5) \quad HX = \phi P_1X + HP_2X$$

and

$$(3.6) \quad LX = LP_2X$$

Lemma 3.2: If \tilde{M} be a $(2n + 1)$ -dimensional nearly Sasakian manifolds, Then

$$(3.7) \quad \tilde{\nabla}_X \xi = -HX - H(\tilde{\nabla}_\xi \phi)X$$

and

$$(3.8) \quad \sigma(X, \xi) = -LX - L(\tilde{\nabla}_\xi \phi)X$$

Proof: Putting $Y = \xi$ in equation (2.4), we get

$$(3.9) \quad (\tilde{\nabla}_\xi \phi)X - \phi(\tilde{\nabla}_X \xi) = \eta(X)\xi - X$$

Operating ϕ , equation (3.9) becomes

$$(3.10) \quad \tilde{\nabla}_X \xi = -\phi X - \phi(\tilde{\nabla}_\xi \phi)X$$

Using equations (2.5)& (2.10), in (3.10) we have the results.

Lemma 3.3: Let M be a semi- slant submanifold of a nearly Sasakian manifold M ,

$$(3.11) \quad \begin{aligned} g([X, Y], \xi) &= 2g(HX, Y) \\ &+ g(Y, H(\tilde{\nabla}_\xi \phi)X) \\ &- g(X, H(\tilde{\nabla}_\xi \phi)Y), \end{aligned}$$

for any $X, Y \in D_2 \oplus D_1$.

Proof: From equations (2.12) and (3.9), we conclude the re

Proposition 3.4: Let M be a semi- slant submanifold of a nearly Sasakian manifold M and the slant distribution D_2 is integrable. Then D_2 is anti-invariant if

$$g(Y, H(\tilde{\nabla}_\xi \phi)X) = g(X, H(\tilde{\nabla}_\xi \phi)Y),$$

holds for all $X, Y \in D_2$.

Proof: For any $[X, Y] \in D_2$, Lemma (3.3) gives

$$g([X, Y], \xi) = 2g(HX, Y)$$

Further, if D_2 is integrable then

$$[X, Y] \in D_2, \text{ means } g([X, Y], \xi) = 0$$

which implies $H = 0$ that means slant angle of D_2 is $\frac{\pi}{2}$

Lemma 3.5: Let M be a semi- slant submanifold of a nearly Sasakian manifold M . Then, for any $X, Y \in TM$, we have

$$\begin{aligned} (3.12) \quad & P^1(\nabla_X \phi P^1 Y) + \\ & P_1(\nabla_X H P_2 Y) + P_1(\nabla_Y \phi P_1 X) + \\ & P_1(\nabla_Y H P_2 X) \\ & = \phi P_1(\nabla_X Y) + P_1 A_{LP^2 Y} X \\ & \quad + \phi P_1(\nabla_Y X) + P_1 A_{LP^2 Y} Y \\ & \quad - \eta(Y) P_1 X - \eta(X) P_1 Y \end{aligned}$$

$$\begin{aligned} (3.13) \quad & P_2(\nabla_X \phi P_2 Y) + P_2(\nabla_X H P_2 Y) \\ & \quad + P_2(\nabla_Y \phi P_1 X) \\ & \quad + P_2(\nabla_Y H P_2 X) \end{aligned}$$

$$\begin{aligned} & = H P_2(\nabla_X Y) + P_2 A_{LP^2 Y} X + 2h\sigma(X, Y) \\ & \quad + H P_2(\nabla_Y X) + P_2 A_{LP^2 X} Y \\ & \quad - \eta(Y) P_2 X - \eta(X) P_2 Y \end{aligned}$$

$$\begin{aligned} (3.14) \quad & \eta(\nabla_X \phi P_2 Y) + \eta(\nabla_X H P_2 Y) \\ & \quad + \eta(\nabla_Y \phi P_1 X) \\ & \quad + \eta(\nabla_Y H P_2 X) \\ & = H P_2(\nabla_X Y) + P_2 A_{LP^2 Y} X + 2h\sigma(X, Y) \\ & \quad + H P_2(\nabla_Y X) + P_2 A_{LP^2 X} Y - \eta(Y) P_2 X \\ & \quad - \eta(X) P_2 Y \end{aligned}$$

$$\begin{aligned} (3.15) \quad & \sigma(\phi P_1 X, Y) + \sigma(\phi P_1 Y, X) \\ & \quad + \sigma(HP_2 X, Y) \\ & \quad + \sigma(HP_2 Y, X) + \nabla_X^\perp LP_2 Y \\ & \quad + \nabla_Y^\perp LP_2 X \end{aligned}$$

$$= LP_2(\nabla_X Y) + LP_2(\nabla_Y X) + 2l\sigma(X, Y)$$

Proof. Using Weingarten formula and equations (2.11), (3.1) & (3.2), equation (2.4) reduces into

$$\begin{aligned} (3.16) \quad & \nabla_X \phi P_1 Y + \\ & \sigma(\phi P_1 Y, X) + \nabla_X HP_2 Y + \sigma(HP_2 Y, X) - \\ & A_{LP^2 Y} X + \nabla_X^\perp LP_2 Y - \phi P_1(\nabla_X Y) - \\ & HP_2(\nabla_X Y) - LP_2(\nabla_X Y) - 2h\sigma(X, Y) - \\ & 2l\sigma(X, Y) + \nabla_Y \phi P_1 X + \sigma(\phi P_1 X, Y) + \\ & \nabla_Y HP_2 X + \sigma(HP_2 X, Y) - A_{LP^2 X} Y + \\ & \nabla_Y^\perp LP_2 X - \phi P_1(\nabla_Y X) - HP_2(\nabla_Y X) - \\ & LP_2(\nabla_Y X) \\ & = 2g(X, Y)\xi - 2\eta(X)\eta(Y)\xi - \eta(Y)P_1 X \\ & \quad - \eta(Y)P_2 X - \eta(X)P_1 Y \\ & \quad - \eta(X)P_2 Y \end{aligned}$$

By identifying the components on $D_1, D_2, \{\xi\}$ and $T^\perp M$, we get the desired results.

4. Parallel Distributions

Definition 4.1: The distribution D is said to be parallel with respect to the connection ∇ on M if $\nabla_X Y \in D$ for all $X, Y \in D$.

Definition 4.2: If a distribution D on M is autoparallel, then it is integrable and according to Gauss and Weingarten formula D is totally geodesic in M .

Definition 4.3: If D is parallel then the orthogonal complementary distribution D^\perp

is also parallel which implies that D is parallel if and only if D^\perp parallel, therefore M is locally the product of the leaves of D and D^\perp

Proposition 4.4: Let M be a semi- slant submanifold of a nearly Sasakian manifold M . Then the distribution $D_1 \oplus \{\xi\}$ is autoparallel if and only if

$$(4.1) \quad \sigma(HX, Y) + \sigma(HY, X) = 2l\sigma(X, Y)$$

Proof. From equation (3.15), we observe that if $X, Y \in D_1 \oplus \{\xi\}$ then

$$\sigma(\phi X, Y) + \sigma(\phi Y, X) = LP_2(\nabla_X Y) + LP_2(\nabla_Y X) + 2l\sigma(X, Y)$$

Since distribution $D_1 \oplus \{\xi\}$ is autoparallel with respect to ∇ on M so for any $X, Y \in D_1 \oplus \{\xi\}$, $\nabla_X Y \in D_1 \oplus \{\xi\}$. Therefore

$$\sigma(\phi X, Y) + \sigma(\phi Y, X) = 2l\sigma(X, Y)$$

and hence the result follows.

Corollary 4.5: The above distribution $D_1 \oplus \{\xi\}$ is also integrable.

Proof : The proof follows due to the fact that any distribution which is auto parallel on M , is integrable.

Proposition 4.6: Let M be a semi- slant submanifold of a nearly Sasakian manifold M . Then the distribution $D_2 \oplus \{\xi\}$ is autoparallel if and only if

$$P_1\nabla_X HY + \nabla_Y HX = P_1(A_{LY}X + A_{LX}Y),$$

for any $X, Y \in D_2 \oplus \{\xi\}$

Proof : Obeying equations (3.5) and (3.6), the results are obtained.

Lemma 4.7: Let M be a submanifolds of a nearly Sasakian manifolds. Then for any $X, Y \in M$, we have

$$(4.7.1) \quad (\tilde{\nabla}_X \phi)Y = (\nabla_X \phi P_1)Y + (\nabla_X H P_2)Y + (\nabla_X L P_2)Y + \sigma(X, \phi P_1 Y) + \sigma(X, H P_2 Y) - h\sigma(X, Y) - l\sigma(X, Y) - A_{LP_2 Y} X$$

And

$$(4.7.2) \quad (\tilde{\nabla}_X \phi)V = (\nabla_X h)V + (\nabla_X l)V + \sigma(X, hV) + \phi P_1 A_V X + H P_2 A_V X + L P_2 A_V X - A_{LV} X$$

Proof : The result is followed by using equation (2.10) and the fact that D_1 is invariant.

Now the equations (2.4), (2.10) along with above equation (4.3) governs the following:

$$(4.2) \quad (\nabla_X \phi P_1)Y + (\nabla_X H P_2)Y + (\nabla_X L P_2)Y + \sigma(X, \phi P_1 Y) + \sigma(X, H P_2 X) - h\sigma(X, Y) - l\sigma(X, Y) - A_{LP_2 Y} X + (\nabla_Y \phi P_1)X + (\nabla_Y H P_2)X + (\nabla_Y L P_2)X + \sigma(Y, \phi P_1 X) + \sigma(Y, H P_2 X) - h\sigma(X, Y) - l\sigma(X, Y) - A_{LP_2 X} Y = 2g(X, Y)\xi - \eta(Y)X - \eta(X)Y$$

On simplification, the equation (4.2) turns into

$$(4.3) \quad (\nabla_X \phi P_1)Y + (\nabla_X HP_2)Y - A_{LP_2Y}X - A_{LP_2X}Y - 2h\sigma(X, Y) + (\nabla_Y HP_2)X + (\nabla_Y \phi P_1)X = 2g(X, Y)\xi - \eta(Y)X - \eta(X)Y$$

and

$$(4.4) \quad (\nabla_X LP_2)Y + (\nabla_Y LP_2)X + \sigma(X, \phi P_1Y) + \sigma(X, HP_2Y) + \sigma(Y, \phi P_1X) + \sigma(Y, HP_2X) - 2l\sigma(X, Y) = 0$$

Further, let $X, Y \in D_1 \oplus \{\xi\}$. Then equation (4.4) reduces into following

$$(4.5) \quad LP_2[X, Y] = 2LP_2(\nabla_X Y) - \sigma(X, \phi P_1Y) - \sigma(Y, \phi P_1X) + 2l\sigma(X, Y)$$

If $D_1 \oplus \{\xi\}$ is integrable, i.e. $[X, Y] \in D_1 \oplus \{\xi\}$. And hence equation (4.5) gives us

$$(4.6) \quad 2LP_2(\nabla_X Y) + 2l\sigma(X, Y) = \sigma(X, \phi P_1Y) + \sigma(Y, \phi P_1X)$$

Again, equation (4.3) can be expressed as,

$$(4.7) \quad HP_2[X, Y] = (\nabla_X \phi P_1)Y + (\nabla_Y \phi P_1)X + 2HP_2(\nabla_X Y) + 2g(X, Y)\xi - \eta(X)Y - \eta(Y)X$$

But integrability of $D_1 \oplus \{\xi\}$ implies that $[X, Y] \in D_1 \oplus \{\xi\}$ for all $X, Y \in D_1 \oplus \{\xi\}$ and hence it is obvious that $HP_2[X, Y] = 0$

so equation (4.7) reduces into

$$(4.8) \quad (\nabla_X \phi P_1)Y + (\nabla_Y \phi P_1)X = \eta(X)Y + \eta(Y)X - 2g(X, Y)\xi - 2HP_2(\nabla_X Y)$$

In view of the above discussion we state the following theorem:

Theorem 4.8: The distribution $D_1 \oplus \{\xi\}$ on a semi-slant submanifold is integrable if and only if

$$(4.8.1) \quad 2LP_2(\nabla_X Y) + 2l\sigma(X, Y) = \sigma(X, \phi P_1Y) + \sigma(Y, \phi P_1X)$$

and

$$(4.8.2) \quad (\nabla_X \phi P_1)Y + (\nabla_Y \phi P_1)X = \eta(X)Y + \eta(Y)X - 2g(X, Y)\xi - 2HP_2(\nabla_X Y)$$

holds for all $X, Y \in D_1 \oplus \{\xi\}$

Corollary 4.9: The distribution $D_1 \oplus \{\xi\}$ is autoparallel if and only if

$$\sigma(Y, \phi P_1X) + \sigma(X, \phi P_1Y) = 2l\sigma(X, Y)$$

and

$$(4.10) \quad (\nabla_X \phi P_1)Y + (\nabla_Y \phi P_1)X = \eta(X)Y + \eta(Y)X - 2g(X, Y)\xi + \eta(X)\phi P_1Y,$$

holds for all $X, Y \in D_1 \oplus \{\xi\}$.

Proof : As $D_1 \oplus \{\xi\}$ is autoparallel and by using (4.6) & (4.8), the proof is straightforward and hence omitted.

REFERENCE

[1] B. Y. Chen: Geometry of slant submanifolds (Katholieke Universiteit Leuven, 1990). [2] A. Lotta: Slant submanifolds in contact geometry, Bull. Math. Soc. Roumanie 39 (1996), 183- 198. [3] N.Papaghiuc: Semi-slant submanifolds of a Kaehlerian manifold. An. Stiint. Al. I. Cuza. Univ. Iasi. 40 (1994), 55- 61. [4] J. L. Cabrerizo, A. Carriazo: L. M. Fernandez and M. Fernandez, Semi-slant submanifolds of a sasakian manifold, Geometriae Dedicata 78(2): 183- 199, 1999. [5] C. Gherghe: Harmonicity on nearly trans- Sasakian manifolds, Demonstratio Mathe-matica Vol. XXXIII, 2000-No. 1,151-157. [6] T. Koufogiorgos, C. Tsihlias: On the existence of a new class of contact metric manifolds, Canad. Math. Bull. Vol. 43 (4), (2000), 440- 447. [7] R. Falleh Al- solamy: CR- Submanifolds of a nearly trans- Sasakian manifold, IJMMS 31(3): 2002, 167-175. [8] Jeong- Sik Kim, Ximin liu and M. M. Tripathi : On semi- invariant submanifolds of nearly trans- Sasakian manifolds, Int. J. Pure & Appl. Math. Sci. Vol. 1(2004) pp. 15-34. [9] A. Bejancu: Geometry of CR- Submanifolds, D. Reidel Publ. Co., Holland, 1986.]